# R&S®NRP-Zxx Power Sensors

# **Specifications**









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## **Definitions**

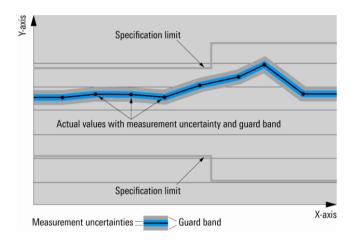
#### Genera

Product data applies under the following conditions:

- · Three hours storage at ambient temperature followed by 30 minutes warm-up operation
- · Specified environmental conditions met
- · Recommended calibration interval adhered to
- All internal automatic adjustments performed, if applicable

#### Specifications with limits

Represent warranted product performance by means of a range of values for the specified parameter. These specifications are marked with limiting symbols such as <,  $\leq$ , >,  $\geq$ ,  $\pm$ , or descriptions such as maximum, limit of, minimum. Compliance is ensured by testing or is derived from the design. Test limits are narrowed by guard bands to take into account measurement uncertainties, drift and aging, if applicable.



#### Specifications without limits

Represent warranted product performance for the specified parameter. These specifications are not specially marked and represent values with no or negligible deviations from the given value (e.g. dimensions or resolution of a setting parameter). Compliance is ensured by design.

#### Typical data (typ.)

Characterizes product performance by means of representative information for the given parameter. When marked with <, > or as a range, it represents the performance met by approximately 80 % of the instruments at production time. Otherwise, it represents the mean value.

#### Nominal values (nom.)

Characterize product performance by means of a representative value for the given parameter (e.g. nominal impedance). In contrast to typical data, a statistical evaluation does not take place and the parameter is not tested during production.

#### Measured values (meas.)

Characterize expected product performance by means of measurement results gained from individual samples.

#### **Uncertainties**

Represent limits of measurement uncertainty for a given measurand. Uncertainty is defined with a coverage factor of 2 and has been calculated in line with the rules of the Guide to the Expression of Uncertainty in Measurement (GUM), taking into account environmental conditions, aging, wear and tear.

Device settings and GUI parameters are indicated as follows: "parameter: value".

Typical data as well as nominal and measured values are not warranted by Rohde & Schwarz.

In line with the 3GPP/3GPP2 standard, chip rates are specified in Mcps (million chips per second), whereas bit rates and symbol rates are specified in Mbps (million bits per second), kbps (thousand bits per second), Msps (million symbols per second) or ksps (thousand symbols per second), and sample rates are specified in Msample/s (million samples per second). Mcps, Mbps, Msps, ksps and Msample/s are not SI units.

# Overview of the R&S®NRP-Zxx power sensors

Sensor type R&S®	Frequency range	Power range, max. average power / peak envelope power	Connector type
Two-path diode p	ower sensors		
NRP-Z211	10 MHz to 8 GHz	1.0 nW to 100 mW (-60 dBm to +20 dBm) max. 400 mW (AVG) / 2 W (PK, 10 µs)	N
NRP-Z221	10 MHz to 18 GHz	1.0 nW to 100 mW (-60 dBm to +20 dBm) max. 400 mW (AVG) / 2 W (PK, 10 µs)	N
Wideband power	sensors		·
NRP-Z81	50 MHz to 18 GHz	1 nW to 100 mW (-60 dBm to +20 dBm) max. 200 mW (AVG) / 1 W (PK, 1 µs)	N
NRP-Z85	50 MHz to 40 GHz	1 nW to 100 mW (-60 dBm to +20 dBm) max. 200 mW (AVG) / 1 W (PK, 1 µs)	2.92 mm
NRP-Z86 model .40	50 MHz to 40 GHz	1 nW to 100 mW (-60 dBm to +20 dBm) max. 200 mW (AVG) / 1 W (PK, 1 µs)	2.40 mm
NRP-Z86 model .44	50 MHz to 44 GHz	1 nW to 100 mW (-60 dBm to +20 dBm) max. 200 mW (AVG) / 1 W (PK, 1 µs)	2.40 mm
Level control sens	sors		'
NRP-Z28	10 MHz to 18 GHz	200 pW to 100 mW (-67 dBm to +20 dBm) max. 700 mW (AVG) / 4 W (PK, 10 µs)	N
NRP-Z98	9 kHz to 6 GHz	200 pW to 100 mW (-67 dBm to +20 dBm) max. 700 mW (AVG) / 4 W (PK, 10 µs)	N
Power sensor mo	dules		
NRP-Z27	DC to 18 GHz	4 µW to 400 mW (-24 dBm to +26 dBm) max. 500 mW (AVG) / 30 W (PK, 1 µs)	N
NRP-Z37	DC to 26.5 GHz	4 µW to 400 mW (-24 dBm to +26 dBm) max. 500 mW (AVG) / 30 W (PK, 1 µs)	3.5 mm

# Specifications in brief of the R&S®NRP-Zxx power sensors

Sensor type	Impedance matching (SWR)	Rise time Zero Video BW offset		Noise (typ.)	Uncertainty for power measurements at +20 °C to +25 °C	
R&S®			(typ.)	(),	absolute	relative
Two-path dioc	le power sensors			'		
NRP-Z211	10 MHz to 2.4 GHz: < 1.13				0.054 dB to	0.022 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20	< 10 µs			0.110 dB	0.112 dB
NRP-Z221	10 MHz to 2.4 GHz: < 1.13	> 40 kHz	290 pW	180 pW	0.054 dB to	0.022 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20		·		0.143 dB	0.142 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
Wideband pov	ver sensors					
NRP-Z81	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20				0.150 dB	0.148 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
NRP-Z85	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
	> 2.4 GHz to 8.0 GHz: < 1.20				0.170 dB	0.165 dB
NRP-Z86	> 8.0 GHz to 18.0 GHz: < 1.25					
model .40	> 18.0 GHz to 26.5 GHz:< 1.30	< 13 ns	220 pW	110 pW		
	> 26.5 GHz to 40.0 GHz:< 1.35	> 30 MHz				
NRP-Z86	50 MHz to 2.4 GHz: < 1.16				0.130 dB to	0.039 dB to
model .44	> 2.4 GHz to 8.0 GHz: < 1.20				0.190 dB	0.165 dB
	> 8.0 GHz to 18.0 GHz: < 1.25					
	> 18.0 GHz to 26.5 GHz:< 1.30					
	> 26.5 GHz to 40.0 GHz:< 1.35					
	> 40.0 GHz to 44.0 GHz:< 1.40					
Level control:						
NRP-Z28	10 MHz to 2.4 GHz: < 1.11	< 8 µs			0.047 dB to	0.022 dB to
	> 2.4 GHz to 4.0 GHz: < 1.15	> 50 kHz			0.130 dB	0.110 dB
	> 4.0 GHz to 8.0 GHz: < 1.22					
	> 8.0 GHz to 18 GHz: < 1.30		67 pW	42 pW		
NRP-Z98	9 kHz to 2.4 GHz: < 1.11	_			0.047 dB to	0.022 dB to
	> 2.4 GHz to 4.0 GHz: < 1.15				0.083 dB	0.066 dB
	> 4.0 GHz to 6.0 GHz: < 1.22					
Power sensor						
NRP-Z27	DC to 2.0 GHz: < 1.15	_			0.070 dB to	0.032 dB
	> 2.0 GHz to 4.2 GHz: < 1.18				0.112 dB	
	> 4.2 GHz to 8.0 GHz: < 1.23					
	> 8.0 GHz to 12.4 GHz: < 1.25					
	> 12.4 GHz to 18.0 GHz:< 1.35		200 nW	120 nW		
NRP-Z37	DC to 2.0 GHz: < 1.15	_			0.070 dB to	0.032 dB
	> 2.0 GHz to 4.2 GHz: < 1.18				0.122 dB	
	> 4.2 GHz to 8.0 GHz: < 1.23					
	> 8.0 GHz to 12.4 GHz: < 1.25					
	> 12.4 GHz to 18.0 GHz:< 1.30					
	> 18.0 GHz to 26.5 GHz:< 1.45					

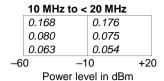
# Two-path power sensors in R&S®Smart Sensor Technology

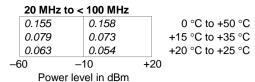
# R&S®NRP-Z211/-Z221 two-path diode universal power sensors

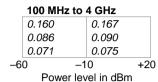
Specifications from 8 GHz to 18 GHz apply only to the R&S®NRP-Z221.

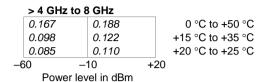
D 9 C®NDD 7011	10 MHz to 9 CHz				
		( ) 45 °C to . 25 °C			
	` ,	( ): +15 °C to +35 °C			
	\ /	ID ( 00 ID )			
	` ,				
		10 μs			
path 2	-33 dBm to +20 dBm				
with automatic path selection <sup>3</sup>	$(-10 \pm 1)$ dBm to $(-4 \pm 1)$	dBm			
video bandwidth	> 40 kHz (50 kHz)				
single-shot bandwidth	> 40 kHz (50 kHz)	( ): +15 °C to +35 °C			
rise time 10 %/90 %	< 10 µs (8 µs)				
sample rate (continuous)	133.358 kHz (default) or	119.467 kHz <sup>4</sup>			
internal					
threshold level range -33 dBm to +20 dBm					
· · · · · · · · · · · · · · · · · · ·					
,	measurements	measurements			
threshold level hysteresis	0 dB to 10 dB				
	0 s to 10 s				
•		R&S®NRP-Z3 USB			
adapter cable or R&S®NRP-Z5 USB s					
l l					
	<u> </u>				
-					
	internal, external, immediate, bus, hold				
initial, without zeroing	internal, external, infined	ate, bus, note			
path 1	< 1.88 [2.0] (0.6) nW				
path 2	< 0.94 [1.0] (0.3) µW				
after external zeroing 6, 7	( ), tomical at 4 Cl				
path 1	< 370 [390] (290) pW	( ): typical at 1 GHz +15 °C to +35 °C			
path 2		+15 0 10 +35 0			
path 1	440 [450] (0) -14/				
	1 1.0 0112 10 10				
	< 60 [65] (0) nW				
path 2	< 60 [65] (0) nW < 230 [240] (180) pW				
	video bandwidth single-shot bandwidth rise time 10 %/90 % sample rate (continuous) internal threshold level range threshold level accuracy  threshold level hysteresis dropout <sup>5</sup> external  slope (external, internal) delay hold-off resolution (delay, hold-off, dropout) source initial, without zeroing path 1 path 2 after external zeroing <sup>6, 7</sup> path 1 path 2	R&S®NRP-Z221  10 MHz to 2.4 GHz  > 2.4 GHz to 8.0 GHz  > 8.0 GHz to 18.0 GHz  > 8.0 GHz to 18.0 GHz  continuous average  1.0 µW to 100 mW (-60 or timeslot/gate average  timeslot/gate average  1.0 µW to 100 mW (-55 or trace  average power  path 1  path 2  video bandwidth  rise time 10 %/90 %  sample rate (continuous)  internal  threshold level range  threshold level accuracy  threshold level hysteresis  delay  for exempted  for exempted  path 1  conditions  continuous  average power  path 1  conditions  conditions  conditions  for max  conditions  cond			

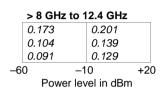
## Uncertainty for absolute power measurements 10 in dB

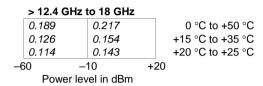




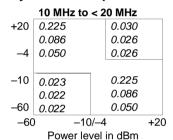


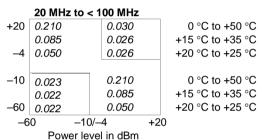


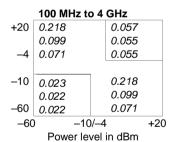


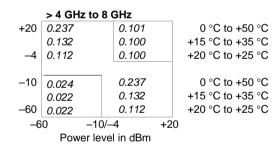


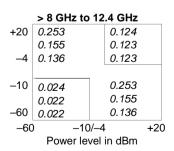
#### Uncertainty for relative power measurements 11 in dB

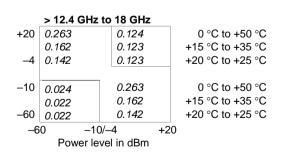












# Additional characteristics of the R&S®NRP-Z211/-Z221 two-path diode power sensors

Sensor type	R&S®NRP-Z211/-Z221	two-path diode power sensor				
Measurand		power of incident wave				
		power of source (DUT) into 50 Ω 12				
RF connector	R&S®NRP-Z211/-Z221	N (male)				
RF attenuation 13	R&S®NRP-Z211/-Z221	not applicable				
Measurement functions	stationary and recurring waveforms	continuous average				
	, ,	burst average				
		timeslot/gate average				
		trace				
	single events	trace				
Continuous average function	measurand	mean power over recurring acquisition interval				
	aperture	10 μs to 300 ms (20 ms default)				
	window function	uniform or von Hann 14				
	duty cycle correction <sup>15</sup>	0.001 % to 99.999 %				
	capacity of measurement buffer <sup>16</sup>	1 to 1024 results				
Burst average function	measurand	mean power over burst portion of				
burst average function	measurand	recurring signal (trigger settings required)				
	detectable burst width	recurring signal (trigger settings required)				
	R&S®NRP-Z211/-Z221	25 µs to 50 ms				
	minimum gap between bursts	10 µs				
	dropout period <sup>17</sup> for burst end detection	0 to 3 ms				
	exclusion periods <sup>18</sup>					
	start	0 to burst width				
	end	0 s to 3 ms				
	resolution (dropout and exclusion periods)	sample period (≈ 8 µs)				
Timeslot/gate average function	measurand	mean power over individual				
·····ooiouguio uvoiugo iuiioiioii	au	timeslots/gates of recurring signal				
	number of timeslots/gates	1 to 128 (consecutive)				
	nominal length	10 μs to 0.1 s				
	start of first timeslot/gate	at delayed trigger event				
	exclusion periods <sup>18</sup>	39				
	start	0 to nominal length				
	end	0 s to 3 ms				
	resolution (nominal length and exclusion periods)	sample period (≈ 8 µs)				
Trace function	measurand	mean power over pixel length				
	acquisition	,oan power over pixer ionigan				
	length (△)	100 µs to 300 ms				
	start (referenced to delayed trigger)	–5 ms to +100 s				
	result					
	pixels (M)	1 to 1024				
	resolution (\(\alpha/M\)	ı				
	non recurring or internally triggered	≥ 10 µs				
	recurring and externally triggered	≥ 2.5 µs				

Averaging filter	modes	auto off (fixed averaging number)		
Averaging inter	modes	auto on (continuously auto-adapted)		
		auto once (automatically fixed once)		
	auto off	auto once (automatically fixed once)		
	supported measurement functions	all		
	averaging number	$2^N$ ; $N = 0$ to 16 (13 for trace function)		
	auto on/once	2 , 77 = 0 to 10 (10 101 trace ranotteri)		
	supported measurement functions	continuous average, burst average,		
	supported measurement functions	timeslot/gate average		
	normal operating mode	averaging number adapted to resolution		
	normal operating mode	setting and power to be measured		
	fixed noise operating mode	averaging number adapted to specified		
	and the second of the second o	noise content		
	result output			
	moving mode	continuous, independent of averaging		
		number		
	rate	can be limited to 0.1 s <sup>-1</sup>		
	repeat mode	only final result		
Attenuation correction	function	corrects the measurement result by		
		means of a fixed factor (dB offset)		
	range	-200.000 dB to +200.000 dB		
Embedding	function	incorporates a two-port device at the		
		sensor input so that the measurement		
		plane is shifted to the input of this device		
	parameters	$S_{11}$ , $S_{21}$ , $S_{12}$ and $S_{22}$ of device		
	frequencies	1 to 1000		
Gamma correction	function	removes the influence of impedance		
		mismatch from the measurement result so		
		that the power of the source (DUT) into 50		
		Ω can be read		
	parameters	magnitude and phase of reflection		
		coefficient of source (DUT)		
Frequency response correction	function	takes the frequency response of the		
		sensor section and of the RF power		
		attenuator into account (if applicable)		
	parameter	center frequency of test signal		
	residual uncertainty	see specification of calibration uncertainty		
		and uncertainty for absolute and relative		
Measurement times 19	acontinuo un autoro de	power measurements		
wicasurement times	continuous average  buffered <sup>16</sup> , without averaging	2 × (aperture + 145 $\mu$ s) × 2 <sup>N</sup> + $t_z$ 2 × (aperture + 166 $\mu$ s) × buffer size + $t_z$		
2 <sup>N</sup> : averaging number		$\angle \times (aperture + 100 \mu s) \times buller size + l_z$		
T: set number of timeslots	timeslot/gate average signal period – $T \times w > 100 \mu s$	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_7$		
w: nominal length of timeslot		$\leq 2 \times \text{signal period} \times (2^{N} + \frac{1}{2}) + t_{z}$ $\leq 4 \times \text{signal period} \times (2^{N} + \frac{1}{4}) + t_{z}$		
w. nominal longer of timesiot	all other cases	$\leq 4 \times \text{signal period} \times (2^{11} + \frac{7}{4}) + \frac{7}{4}$ $t_z$ : < 1.6 ms		
Measurement speed	continuous average	ı <sub>Z</sub> . ∼ 1.0 IIIO		
without averaging	single-triggered	550 s <sup>-1</sup> (typ.)		
aperture time = 10 µs	buffered <sup>16</sup>	3000 s <sup>-1</sup> (typ.)		
Zeroing (duration)	depends on setting of averaging filter	, σσσσ σ (ιζιρ.)		
Loi Sing (daration)	auto on	4 s		
	auto off auto off, integration time 20	,		
	< 4 s	4 s		
	4 s to 16 s	integration time		
	> 16 s	16 s		
	, , , , , ,	1		

Measurement error due to	R&S®NRP-Z211/-Z221: all paths	n = 2	n = 3	n: multiple			
harmonics <sup>21</sup>	–30 dBc	< 0.001 dB	< 0.003 dB	of carrier			
	–20 dBc	< 0.002 dB	< 0.010 dB	frequency			
	–10 dBc	< 0.010 dB	< 0.040 dB				
Measurement error due to modulation <sup>22</sup>	general	depends on CO signal	CDF and RF band	dwidth of test			
	WCDMA (3GPP test model 1-64)						
	worst case	-0.02 dB to +0	.07 dB				
	typical	-0.01 dB to +0	.03 dB				
Change of input reflection co-	of input reflection co- R&S®NRP-Z211/-Z221						
efficient with respect to power 23	10 MHz to 2.4 GHz	< 0.02 (0.01)	(): +15 °C to	+35 °C			
	> 2.4 GHz	< 0.03 (0.02)					
Calibration uncertainty 24	R&S <sup>®</sup> NRP-Z211/-Z221	path 1	path 2				
	10 MHz to < 100 MHz	0.052 dB	0.053 dB				
	100 MHz to 4.0 GHz	0.061 dB	0.062 dB				
	> 4.0 GHz to 8.0 GHz	0.075 dB	0.076 dB				
	> 8.0 GHz to 12.4 GHz	0.080 dB	0.080 dB				
	> 12.4 GHz to 18.0 GHz	0.101 dB	0.102 dB				
Interface to host	power supply	+5 V/0.2 A (US	B high-power de	vice)			
	remote control		as a USB device (function) in full-speed mode, compatible with USB 1.0/1.1/2.0 specifications				
	trigger input	differential (0 V	//+3.3 V)				
	connector type	ODU Mini-Sna	p <sup>®</sup> L series,				
		six-pole cylindrical straight plug					
	permissible total cable length	≤ 10 m (see als	so tables on page	28)			
Dimensions (W × H × L)	R&S®NRP-Z211/-Z221	48 mm × 31 mr	48 mm × 31 mm × 170 mm				
•		(1.89 in × 1.22	in × 6.69 in)				
	length including connecting cable	approx. 1.6 m (	approx. 1.6 m (62.99 in)				
Weight	R&S®NRP-Z211/-Z221	< 0.30 kg (0.66	ib)				

# Wideband power sensors in R&S®Smart Sensor Technology

# R&S®NRP-Z81/-Z85/-Z86 wideband power sensors

Specifications from DC to 18 GHz apply to the R&S®NRP-Z81. Specifications from DC to 40 GHz apply to the R&S®NRP-Z85 and R&S®NRP-Z86 model .40. Specifications from DC to 44 GHz apply to the R&S®NRP-Z86 model .44.

Frequency range	R&S®NRP-Z81	50 MHz to 18 GHz			
3.	R&S®NRP-Z85	50 MHz to 40 GHz			
	R&S®NRP-Z86 model .40	50 MHz to 40 GHz			
	R&S®NRP-Z86 model .44	50 MHz to 44 GHz			
Impedance matching (SWR)	50 MHz to 2.4 GHz	< 1.16 (1.11)			
	> 2.4 GHz to 8.0 GHz	< 1.20 (1.18)			
	> 8.0 GHz to 18.0 GHz	< 1.25 (1.23) ( ): +15 °C to +3			
	> 18.0 GHz to 26.5 GHz	< 1.30 (1.28)	()		
	> 26.5 GHz to 40.0 GHz	< 1.35 (1.33)	-		
	> 40.0 GHz to 44.0 GHz	< 1.40 (1.38)	-		
Power measurement range	continuous average	1 nW to 100 mW (–60 dB)	m to +20 dBm)		
	burst	1 ( 35 42.	,		
	full video bandwidth	20 μW to 100 mW (–17 di	3m to +20 dBm)		
	300 kHz	4 μW to 100 mW (–24 dB)			
	trace, timeslot/gate	20 nW to 100 mW (–47 dB			
	statistics	4 μW <sup>25</sup> to 100 mW (–24 c			
Max. power	average power	0.2 W (+23 dBm), continu			
max. power	peak envelope power	1.0 W (+30 dBm) for max.			
Dynamic response	video bandwidth	≥ 30 MHz <sup>26</sup>	ι μο		
Dynamic response	single-shot bandwidth	≥ 30 MHz <sup>26</sup>			
	video bandwidth setting	full (≥ 30 MHz), 5 MHz, 1.5 MHz, 300 kHz			
	rise time 10 %/90 %	1011 (= 30 IVII 12), 3 IVII 12, 1.	5 WII 12, 500 KI 12		
	full video bandwidth	≤ <b>13 ns</b> <sup>26</sup> (f ≥ 500 MHz)			
	Tuli Video baridwidii i	< 40 ns <sup>26</sup> (f < 500 MHz)			
	5 MHz	< 75 ns			
	1.5 MHz	< 250 ns			
	300 kHz	< 1.2 μs			
	detectable burst width	≥ 50 ns <sup>26</sup> (f ≥ 500 MHz, full video bandwidth			
	overshoot	≥ 50 fis * (i ≥ 500 iviH2, full video balldwidth) ≤ 5 %			
Acquisition	sample rate [period]				
Aoquisition	full video bandwidth	$80 \times 10^6 \mathrm{s}^{-1} [12.5 \mathrm{ns}]$			
	5 MHz	$40 \times 10^6 \text{ s}^{-1} [25.0 \text{ ns}]$			
	1.5 MHz	10 x 10 <sup>6</sup> s <sup>-1</sup> [100 ns]			
	300 kHz	$2.5 \times 10^6 \mathrm{s}^{-1} [400 \mathrm{ns}]$			
	capture length	50 ns to 1 s (depending of	n mass function)		
	time base accuracy	±50 ppm	irineas. idiletion)		
	time base jitter	< 1 ns			
Triggering	internal	< 1 113			
mggering	threshold level range	-30 dBm to +20 dBm (usa	able from		
	till esticia level range	-22 dBm with full video ba			
	threshold level accuracy	identical to uncertainty for			
	threshold level decardey	measurements	aboolate power		
	threshold level hysteresis	0 dB to 10 dB			
	dropout <sup>5</sup>	0 s to 10 s			
		see R&S®NRX base unit,	D&C®NDD 73 LICE		
	external	adapter cable or R&S®NR			
	slope (external, internal)	pos./neg.	. 20 000 3611301 11ub		
	delay	–51.2 µs to +10 s			
	hold-off	0 s to 10 s			
	resolution (delay, hold-off, dropout)				
	source	sample period	ata hus hold		
	Source	internal, external, immediate, bus, hold			

Zero offset		R&S®NRP-Z81	R&S®NRP-Z85/-Z86					
After external zeroing <sup>27</sup>	continuous average							
(): typical at 1 GHz	10 µs aperture time	< 400 (220) pW	< 460 (235) pW					
	other durations	< 10.0 (2.0) nW	< 11.4 (2.2) nW					
	burst/timeslot/gate average, trace	(pixel mean)						
	with averaging	< 10.0 (2.0) nW	< 11.4 (2.2) nW					
	without averaging	< 200 (100) nW	< 230 (110) nW					
	statistics	< 200 (100) nW	< 230 (110) nW					
Zero drift 8, 27		R&S®NRP-Z81	R&S®NRP-Z85/-Z86					
	continuous average	'	'					
	10 µs aperture time	< 200 pW	< 230 pW					
	other durations	< 500 pW	< 570 pW					
	burst/timeslot/gate average, trace	burst/timeslot/gate average, trace (pixel mean)						
	with averaging	< 2.0 nW	< 2.3 nW					
	without averaging	< 150 nW	< 170 nW					
	statistics	< 150 nW	< 170 nW					
Measurement noise 27, 28		R&S®NRP-Z81	R&S®NRP-Z85/-Z86					
(): typical at 1 GHz	continuous average <sup>29</sup>							
	10 µs aperture time	< 200 (110) pW	< 230 (120) pW					
	other durations < 5.0 (1.0) nW		< 5.7 (1.1) nW					
	trace/statistics (noise per sample)							
	full video bandwidth	< <b>3.0</b> (2.0) μW	< <b>3.5</b> (2.2) μW					
	5 MHz	< 1.5 (1.0) µW	< 1.7 (1.1) µW					
	1.5 MHz	< 0.9 (0.6) µW	< 1.0 (0.7) µW					
	300 kHz	< 0.6 (0.4) µW	< 0.7 (0.5) µW					
	burst/timeslot/gate average	Multiply the noise-per	-sample specification for					
	trace (pixel mean)	full video bandwidth w	vith noise reduction factors					
	,	from tables B and C. I	For gate (pixel) lengths					
			of 5 nW or better can be					
		achieved with adequa	te averaging.					
Uncertainty for absolute power		R&S®NRP-Z81	R&S®NRP-Z85/-Z86					
measurements 30	50 MHz to < 100 MHz	0.15 dB (3.5 %)	0.15 dB (3.5 %)					
0 °C to +50 °C	100 MHz to 8.0 GHz	0.13 dB (3.0 %)	0.13 dB (3.0 %)					
	> 8.0 GHz to 18.0 GHz	0.15 dB (3.5 %)	0.15 dB (3.5 %)					
	> 18.0 GHz to 26.5 GHz		0.15 dB (3.5 %)					
	> 26.5 GHz to 40.0 GHz	_	0.17 dB (4.0 %)					
	> 40.0 GHz to 44.0 GHz	_	0.19 dB (4.5 %)					

# Uncertainty for relative power measurements <sup>31</sup> in dB

+20	0.179		0.116		0.064	
	0.155		0.105		0.058	
	0.148		0.102		0.056	
+10	0.145		0.094		0.116	
	0.114		0.079		0.105	
-15	0.105		0.075		0.102	
	0.064		0.145		0.179	
	0.045		0.114		0.155	
-60	0.039		0.105		0.148	
	-60	-15	5	+1	10	+20

Power level in dBm

1 GHz to 18 GHz

	50 MHz to > 18 GHz to					
+20	0.193	0.130		0.088		0 °C to +50 °C
	0.170	0.120		0.083		+15 °C to +35 °C
	0.165	0.117		0.083		+20 °C to +25 °C
+10	0.162	0.110		0.130		0 °C to +50 °C
	0.134	0.098		0.120		+15 °C to +35 °C
-15	0.126	0.095		0.117		+20 °C to +25 °C
10	0.068	0.162		0.193		0 °C to +50 °C
	0.051	0.134		0.170		+15 °C to +35 °C
-60	0.046	0.126		0.165		+20 °C to +25 °C
	<del>-</del> 60 -	15	+1	10	+20	
	F	ower level	in d	Bm		

### Table A Multipliers for zero offset, zero drift and noise specifications

Use these multipliers to calculate zero offset, zero drift and noise when operating the sensor at power levels above –20 dBm, at frequencies below 500 MHz, or at temperatures other than +23 °C.

Powe	r ≤ –20 dBm	-10 dBm	–5 dBm	0 dBm	5 dBm	10 dBm	15 dBm	20 dBm
Temperature								
0 °C	<b>0.8</b> [0.9]	<b>0.9</b> [1.0]	<b>1.4</b> [1.5]	<b>3.2</b> [3.5]	<b>7.5</b> [8.5]	<b>17</b> [18]	<b>35</b> [37]	<b>65</b> [70]
+15 °C	<b>0.9</b> [1.0]	<b>1.1</b> [1.2]	<b>1.6</b> [1.8]	<b>3.4</b> [3.6]	<b>7.5</b> [8.5]			
+23 °C	<b>1.0</b> [1.2]	<b>1.3</b> [1.5]	<b>1.8</b> [2.0]	<b>3.5</b> [3.8]	<b>7.6</b> [8.7]			
+35 °C	<b>1.4</b> [1.7]	<b>1.7</b> [2.1]	<b>2.3</b> [2.6]	<b>3.9</b> [4.3]	<b>7.8</b> [9.0]			
+50 °C	<b>2.5</b> [3.0]	<b>2.7</b> [3.3]	<b>3.3</b> [4.0]	<b>5.2</b> [5.4]	<b>8.7</b> [9.5]			

[ ] At frequencies < 500 MHz.

### Table B Noise reduction factors for gating and smoothing

The noise reduction factors in this table describe how measurement noise is reduced if the mean value of adjacent samples is taken over a time interval. The time interval can be the length of a gate, timeslot, or pixel in trace mode. Without averaging or for single events, use the leftmost column. If averaging is activated, use the columns for the individual repetition rates and additionally apply multipliers from table C. The repetition rate is identical to the frequency of the measurement being carried out, i.e. the inverse of the trigger period.

Repetition rate	0	10 s <sup>-1</sup>	100 s <sup>-1</sup>	10 <sup>3</sup> s <sup>-1</sup>	10 <sup>4</sup> s <sup>-1</sup>	$5 \times 10^4  \text{s}^{-1}$	10 <sup>5</sup> s <sup>-1</sup>
Gate							
(pixel) length							
25 ns				0.7			
50 ns				0.5			
100 ns		0.4					
200 ns				0.3			
500 ns				0.2			
1 µs	0.16		0.15		0.14		
2 µs	0.14	0.13	0.12	0.11		0.10	
10 µs	0.11	0.1	0.09	0.08	0.07	0.06	
100 µs	0.10	0.09	0.07	0.06	0.04		
1 ms	0.10	0.07	0.06	0.035			
10 ms	0.10	0.06	0.035				

#### Table C Noise reduction factors for averaging

Averaging number	2	4	8	16	32	64	128	256	512	1k	2k	4k	8k
Reduction factor	0.7	0.5	0.35	0.25	0.18	0.13	0.09	0.063	0.044	0.031	0.022	0.016	0.011

Example: A power measurement on a radar pulse is carried out by means of the timeslot/gate function. The gate length is set to 1  $\mu$ s, and the averaging number to 32. The pulse repetition rate is 100 Hz, and the measurement is performed at +15 °C ambient temperature. The pulse power is about -10 dBm.

From the specifications, a  $2\sigma$  noise-per-sample value of 2  $\mu$ W (typ.) can be derived for reference conditions. Applying a multiplier of 1.1 from table A for +15 °C ambient temperature and -10 dBm pulse power results in 2.2  $\mu$ W sampling noise under measurement conditions. Gating reduces noise by a factor of 0.15 (table B), and averaging further reduces noise by a factor of 0.18 (table C). The residual  $2\sigma$  noise of mean power within the gate can then be calculated as follows: 2.2  $\mu$ W × 0.15 × 0.18 = 59 nW (0.06 % of measured value).

# Additional characteristics of the R&S®NRP-Z81/-Z85/-Z86 wideband power sensors

Sensor type		wideband diode power sensor	
Measurand		power of incident wave	
		power of source (DUT) into 50 Ω <sup>12</sup>	
RF connector	R&S®NRP-Z81	N (male)	
	R&S®NRP-Z85	2.92 mm (male)	
	R&S®NRP-Z86	2.40 mm (male)	
Measurement functions	stationary and recurring waveforms	continuous average	
Medadarement randitions	Stationary and recurring wavelering	burst	
		timeslot/gate	
		trace, statistics	
	single events	trace, statistics	
Continuous average function	measurand	mean power over recurring acquisition interval	
continuous average function	aperture	1 µs to 1 s (10 µs default)	
	window function	uniform or von Hann 14	
	duty cycle correction <sup>15</sup>	0.001 % to 99.999 %	
Donat according from atlan	capacity of measurement buffer 16	1 to 8192 results	
Burst average function	measurand	mean power over burst portion of recurring signa	
		(trigger settings required)	
	detectable burst width	50 ns to 0.1 s	
	minimum gap between bursts	40 ns	
	dropout period <sup>17</sup> for burst end	0 s to 0.1 s	
	detection		
	exclusion periods 18		
	start	0 to burst width	
	end	0 s to 51.2 μs	
	resolution	sample period	
	(dropout and exclusion periods)		
Timeslot/gate function	measurand	mean, maximum and minimum power over	
		individual timeslots/gates of recurring signal	
	number of timeslots/gates	1 to 16 (consecutive)	
	nominal length	50 ns to 0.1 s	
	start of first timeslot/gate	at delayed trigger event	
	exclusion periods 18		
	start	0 to nominal length	
	fence	0 s to 0.1 s (anywhere within timeslot)	
	end	0 s to 51.2 μs	
	resolution	12.5 ns	
	(nominal length and exclusion periods)		
Trace function	measurand	mean, random, maximum and minimum power	
		over pixel length	
	acquisition		
	length (△)	50 ns to 1 s	
	start (referenced to delayed trigger)	$-4096 \times \Delta/M$ to +10 s	
	result		
	pixels (M)	3 to 8192	
	resolution (△/M)	1 - 1 - 1	
	normal	≥ sample period	
	equivalent time	≥ 100 ps	
	automatic pulse measurements	pulse width, pulse period, pulse off time,	
	automatic palce measurements	pulse duty cycle, pulse rise time, pulse fall time,	
		pulse start time, pulse stop time,	
		pulse start time, pulse stop time, pulse top power, pulse base power,	
		pulse peak power, pulse average power,	
		positive overshoot, negative overshoot	

Statistics functions	magaurand	CCDF or PDF over accumulated records			
Statistics functions	measurand	CCDF of FDF over accumulated records			
	acquisition				
	mode	recurring or triggered			
	length (aperture)	10 μs to 0.3 s			
	start (referenced to delayed trigger)	0 s to +10 s			
	exclusion period (fence)	0 s to 0.3 s (anywhere within aperture)			
	number of accumulated records	$2^{N}$ ; $N = 0$ to 16 (set by averaging number)			
	result				
	number of histogram classes (C)	3 to 8192			
	power span (S)	0.01 dB to 100 dB			
	minimum class width (S/C)	0.006 dB			
Averaging filter	modes	auto off (fixed averaging number)			
		auto on (continuously auto-adapted)			
		auto once (automatically fixed once)			
	auto off				
	supported measurement functions	all			
	averaging number	$2^N$ ; $N = 0$ to 20 (16 for trace/statistics)			
	auto on/once				
	supported measurement functions	continuous average, burst average, timeslot/gate			
		average			
	normal operating mode	averaging number adapted to resolution setting			
		and power to be measured			
	fixed noise operating mode	averaging number adapted to specified noise			
		content			
	result output				
	moving mode	continuous, independent of averaging number			
	rate	can be limited to 0.1 s <sup>-1</sup>			
	repeat mode	only final result			
Attenuation correction	function	corrects the measurement result by means of a			
		fixed factor (dB offset)			
	range	-200.000 dB to +200.000 dB			
Embedding	function	incorporates a two-port device at the sensor input			
3		so that the measurement plane is shifted to the			
		input of this device			
	parameters	$S_{11}$ , $S_{21}$ , $S_{12}$ and $S_{22}$ of device			
	number of devices	user-definable			
	frequencies (sum of all devices)	≤ 32000			
Gamma correction	function	removes the influence of impedance mismatch			
Gainina Gorrosaion	Tarronom	from the measurement result so that the power of			
		the source (DUT) into 50 $\Omega$ can be read			
	parameters	magnitude and phase of reflection coefficient of			
	parameters	source (DUT)			
Frequency response correction	function	takes the frequency response of the power			
	13.100011	sensor into account			
	parameter	center frequency of test signal			
	residual uncertainty	see specification of calibration uncertainty and			
	1001dual uncertainty	uncertainty for absolute power measurements			
Measurement time 19	continuous average	ansortainty for absolute power measurements			
weasurement unit	single-triggered	$2 \times (aperture + 6.5 \mu s) \times 2^N + t_z$			
2 <sup>N</sup> : averaging number	buffered <sup>16</sup> , without averaging	2 × (aperture + 5.5 µs) × 2" + $t_z$ 2 × (aperture + 50 µs) × buffer size + $t_z$			
T: number of timeslots	bulleted , without averaging	$t_z$ : < 1.6 ms			
w: nominal length of timeslot	timoslot/gato avorago	t <sub>Z</sub> . ∼ 1.0 III3			
w. nominal length of timesiot	timeslot/gate average	< signal paried + (2N + 1) + 4			
	signal period – $T \times w > 6 \mu s$	$\leq$ signal period $\times$ (2 <sup>N</sup> + 1) + $t_1$ $\leq$ 2 $\times$ signal period $\times$ (2 <sup>N</sup> + $\frac{1}{2}$ ) + $t_1$			
	all other cases				
Management and a state		$t_{\rm t}$ : 3 ms (typ.)			
Measurement speed	continuous average	060 e-1 (h.m.)			
without averaging	single-triggered	960 s <sup>-1</sup> (typ.)			
aperture time = 1 µs	buffered <sup>16</sup>	9800 s <sup>-1</sup> (typ.)			

## Version 12.00, April 2019

Zeroing (duration)	including all functions, entire	8 s			
	frequency range	1 , 0			
	restricted to < 500 MHz, all functions	4 s			
	restricted to ≥ 500 MHz, all functions	4 s			
	restricted to trace and statistics	20 ms			
function, entire frequency range					
Measurement error due to	n = 3	≤ 4 GHz 4 GHz to 12.4 GHz >	12.4 GHz		
harmonics 32	–60 dBc	< 0.004 dB < 0.003 dB < 0.003	003 dB		
	–40 dBc	< 0.035 dB < 0.030 dB < 0.0	025 dB		
n: multiple of carrier frequency	–20 dBc	< 0.350 dB < 0.300 dB < 0.3	250 dB		
	n = 2	≤ 4 GHz 4 GHz to 8 GHz >	8 GHz		
	-60 dBc	< 0.001 dB < 0.002 dB < 0.002	003 dB		
	–40 dBc	< 0.010 dB < 0.017 dB < 0.0	025 dB		
	–20 dBc	< 0.100 dB < 0.170 dB < 0.1	250 dB		
Change of input reflection	-10 dBm to -60 dBm	< 0.035 (0.010)			
coefficient with respect to	-10 dBm to 0 dBm	< 0.035 (0.025) ( ): f ≤ 4 GH	( ): <i>f</i> ≤ 4 GHz		
power <sup>33</sup>	-10 dBm to +10 dBm	< 0.075 (0.055) +15 °C to	+15 °C to +35 °C		
	-10 dBm to +20 dBm	< 0.090 (0.080)			
Calibration uncertainty 34		R&S®NRP-Z81 R&S®NRP-Z	Z85/-Z86		
•	50 MHz to < 100 MHz	0.065 dB (1.5 %) 0.069 dB (1	.6 %)		
	≥ 100 MHz to 2.4 GHz	0.052 dB (1.2 %) 0.052 dB (1	.2 %)		
	> 2.4 GHz to 4.0 GHz	0.052 dB (1.2 %) 0.056 dB (1			
	> 4.0 GHz to 8.0 GHz	0.056 dB (1.3 %) 0.060 dB (1	.4 %)		
	> 8.0 GHz to 12.5 GHz	0.073 dB (1.7 %) 0.073 dB (1	.7 %)		
	> 12.5 GHz to 18.0 GHz	0.086 dB (2.0 %) 0.090 dB (2	.1 %)		
	> 18.0 GHz to 26.5 GHz		0.086 dB (2.0 %)		
	> 26.5 GHz to 40.0 GHz	- 0.116 dB (2	.7 %)		
	> 40.0 GHz to 44.0 GHz	- 0.149 dB (3	2.5 %)		
Interface to host	power supply	+5 V/0.5 A (USB high-power device)			
	remote control	as a USB device (function) in full-spee	ed mode,		
		compatible with USB 1.0/1.1/2.0 specifications			
	trigger input	differential (0 V/+3.3 V)			
	connector type	ODU Mini-Snap® L series,			
		six-pole cylindrical straight plug			
	permissible total cable length	≤ 5 m (see also tables on page 28)			
Dimensions	W×H×L	48 mm × 31 mm × 170 mm			
		$(1.89 \text{ in} \times 1.22 \text{ in} \times 6.69 \text{ in})$			
	length including connecting cable	approx. 1.6 m (62.99 in)			
Weight	<u> </u>	< 0.30 kg (0.66 lb)			

# Level control sensors in R&S®Smart Sensor Technology

# R&S®NRP-Z28 level control sensor

Frequency range		10 MHz to 1	8 GHz		
Impedance matching (SWR) and		input	output	insertion loss 36	
insertion loss		SWR	SWR 35	(): typical	
	10 MHz to 2.4 GHz	< 1.35	< 1.11	< <b>8.0</b> (7.0) dB	
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< <b>8.5</b> (7.5) dB	
	> 4.0 GHz to 8.0 GHz	< 1.75	< 1.22	< <b>9.5</b> (8.5) dB	
	> 8.0 GHz to 12.4 GHz	< 1.80	< 1.30	< <b>10.5</b> (9) dB	
	> 12.4 GHz to 18.0 GHz	< 1.90	< 1.30	< <b>11.0</b> (10) dB	
Power measurement range	continuous average	200 pW to 1	00 mW (–67	dBm to +20 dBm)	
RF output	burst average			dBm to +20 dBm)	
•	timeslot/gate average			dBm to +20 dBm) 1	
	trace			Bm to +20 dBm) 2	
Max. power	average power		,	,	
RF input	10 MHz to 2.4 GHz	0.7 W (+28.	5 dBm)		
	> 2.4 GHz to 8.0 GHz	0.9 W (+29.		continuous	
	> 8.0 GHz to 12.4 GHz	1.1 W (+30.			
	> 12.4 GHz to 18.0 GHz	1.3 W (+31.			
	peak envelope power			ge power (for 10 µs)	
Measurement subranges	path 1	-67 dBm to		go power (for to po)	
measurement subranges	path 2				
	path 3	-46 dBm to +6 dBm -26 dBm to +20 dBm			
Transition regions	with automatic path selection <sup>3</sup>	(-19 -1/+2) dBm to (-13 -1/+2) dB		/+2) dBm	
Transition regions	with automatic path selection		3m to (+7 –1/+2		
Dynamic response	video bandwidth	> 50 kHz (1		, abiii	
Dynamic response	single-shot bandwidth	> 50 kHz (1		( ): +15 °C to +35 °C	
	rise time 10 %/90 %	< 8 µs (4 µs)		(). +13 0 10 +33 0	
Acquisition	sample rate (continuous)	133.358 kHz (default) or 119.467 kHz <sup>4</sup>		110 467 kHz 4	
Triggering	. , ,	133.336 KH	z (deladit) oi	119.407 KHZ	
mggemg	internal threshold lovel range 40 dPm to 120 dPm				
	threshold level range —40 dBm to +20 dBm		chaoluta nowar		
	threshold level accuracy identical to uncertainty for absolute p		absolute power		
	threshold level hysteresis 0 dB to 10 dB				
	threshold level hysteresis dropout <sup>5</sup>	0 s to 10 s	טו		
	external		DV boso unit	R&S®NRP-Z3 USB	
	external		,		
	alana (aytarnal internal)	<u> </u>	ie oi kasink	RP-Z5 USB sensor hub	
	slope (external, internal)	pos./neg. -5 ms to +1	00.0		
	delay hold-off		00 8		
	resolution (delay, hold-off, dropout)	0 s to 10 s			
		sample period internal, external, immediate, bus, hold			
7	source	internal, ext	emai, immedi	ate, bus, noid	
Zero offset	initial, without zeroing	FOE [COO]	(400) =\//		
	path 1	< 505 [600]			
	path 2	< 52 [60] (10	, , , ,		
	path 3	< 5.2 [6] (1)	μνν	( ), turning of at 1 CLIT	
	after external zeroing 6,7	44454001	(07) 14/	( ): typical at 1 GHz +15 °C to +35 °C	
	path 1	< 114 [132]		+15 0 10 +35 0	
	path 2	< 11 [13] (6)		[ ]: 0 CU- +- 40 CU-	
	path 3	< 1.1 [1.3] (		[ ]: 8 GHz to 18 GHz	
Zero drift <sup>8</sup>	path 1	< 39 [44] (0)			
	path 2	< 3.3 [3.8] (			
	path 3	< 0.33 [0.38			
Measurement noise 9	path 1	< 72 [83] (43			
	path 2	< 7 [8] (4) n			
	path 3	< 0.7 [0.8] (	0.4) µW		

-67

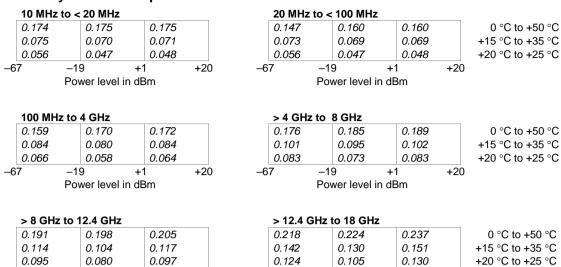
-19

+1

Power level in dBm

+20

## Uncertainty for absolute power measurements 10 in dB



-67

-19

+1

Power level in dBm

+20

# Uncertainty for relative power measurements <sup>11</sup> in dB

	10 MHz to	< 20 MHz			
+20	0.226	0.229	0.027		
	0.084	0.080	0.022		
+7	0.046	0.044	0.022		
			_		
+1	0.226	0.027	0.229		
	0.083	0.022	0.080		
-13	0.045	0.022	0.044		
-19	0.023	0.226	0.226		
	0.022	0.083	0.084		
-67	0.022	0.045	0.046		
-6	7 –19/-	-13 ±0/	+8 +20		
Power level in dBm					

	20 MHz t	o < 100 MHz					
+20	0.206	0.215	0.027	0 °C to +50 °C			
	0.082	0.078	0.022	+15 °C to +35 °C			
+7	0.046	0.044	0.022	+20 °C to +25 °C			
			_				
+1	0.205	0.027	0.215	0 °C to +50 °C			
	0.081	0.022	0.078	+15 °C to +35 °C			
-13	0.044	0.022	0.044	+20 °C to +25 °C			
		_					
-19	0.023	0.205	0.206	0 °C to +50 °C			
	0.022	0.081	0.082	+15 °C to +35 °C			
-67	0.022	0.044	0.046	+20 °C to +25 °C			
_	67 –1	9/–13 ±0	0/+8 +2	0			
	Power level in dBm						

	100 MHz to	o 4 GHz			
+20	0.209	0.218	0.038		
	0.088	0.085	0.032		
+7	0.055	0.047	0.031		
			_		
+1	0.206	0.028	0.218		
	0.083	0.022	0.085		
-13	0.048	0.022	0.047		
-19	0.023	0.206	0.209		
	0.022	0.083	0.088		
-67	0.022	0.048	0.055		
-6	57 –19/	–13         +1/	+7 +20		
Power level in dBm					

	> 4 GHz to	8 GHz				
+20	0.215	0.223	0.049	0 °C to +50 °C		
	0.097	0.093	0.044	+15 °C to +35 °C		
+7	0.066	0.059	0.043	+20 °C to +25 °C		
+1	0.210	0.030	0.223	0 °C to +50 °C		
	0.088	0.022	0.093	+15 °C to +35 °C		
-13	0.054	0.022	0.059	+20 °C to +25 °C		
-19	0.024	0.210	0.215	0 °C to +50 °C		
	0.022	0.088	0.097	+15 °C to +35 °C		
-67	0.022	0.054	0.066	+20 °C to +25 °C		
-(	67 –19/	/_13 +1	/+7 +2	20		
Power level in dBm						

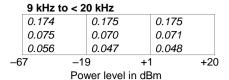
	> 8 GHz to	12.4 GHz			
+20	0.224	0.231	0.064		
	0.111	0.106	0.061		
+7	0.084	0.077	0.060		
+1	0.216	0.034	0.231		
	0.096	0.027	0.106		
-13	0.063	0.025	0.077		
-19	0.024	0.216	0.224		
	0.022	0.096	0.111		
-67	0.022	0.063	0.084		
-6	7 –19/-	-13 +1/	+7 +20		
Power level in dBm					

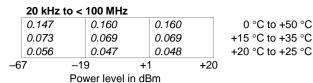
	> 12.4 GHz	to 18 GHz				
+20	0.244	0.245	0.086	0 °C to +50 °C		
	0.135	0.128	0.084	+15 °C to +35 °C		
+7	0.110	0.102	0.083	+20 °C to +25 °C		
			_			
+1	0.230	0.040	0.245	0 °C to +50 °C		
	0.112	0.034	0.128	+15 °C to +35 °C		
-13	0.079	0.033	0.102	+20 °C to +25 °C		
-19	0.024	0.230	0.244	0 °C to +50 °C		
	0.022	0.112	0.135	+15 °C to +35 °C		
-67	0.022	0.079	0.110	+20 °C to +25 °C		
_	67 –19/	_13 +1	/+7 -	<del>-</del> 20		
Power level in dBm						

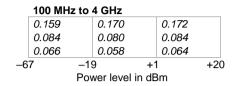
# R&S®NRP-Z98 level control sensor

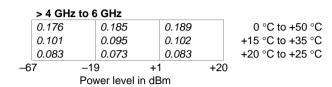
Frequency range		9 kHz to 6	GHz		
Impedance matching (SWR) and insertion loss		input output SWR SWR 35		insertion loss <sup>36</sup> ( ): typical	
	9 kHz to 2.4 GHz	< 1.35	< 1.11	< 8.0 (7.0) dB	
	> 2.4 GHz to 4.0 GHz	< 1.45	< 1.15	< 8.5 (7.5) dB	
	> 4.0 GHz to 6.0 GHz	< 1.75	< 1.22	< 9.5 (8.5) dB	
Power measurement range RF output	continuous average	200 pW to	100 mW (–67	dBm to +20 dBm)	
Max. power	average power				
RF input	9 kHz to 2.4 GHz	0.7 W (+28	.5 dBm)	continuous	
	> 2.4 GHz to 6.0 GHz	0.9 W (+29	.5 dBm)		
	peak envelope power	7.5 dB abo	ve max. avera	ge power (for 10 µs)	
Measurement subranges	path 1	−67 dBm to	-67 dBm to -14 dBm		
	path 2	-46 dBm to	-46 dBm to +6 dBm		
	path 3	-26 dBm to +20 dBm			
Transition regions	with automatic path selection <sup>3</sup>	,	(-19 -1/+2) dBm to (-13 -1/+2) dBm (+1 -1/+2) dBm to (+7 -1/+2) dBm		
Dynamic response	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \				
Acquisition	sample rate (continuous)	133.358 kH	łz		
Zero offset	initial, without zeroing				
	path 1	< 505 (100			
	path 2	< 52 (10) n	W		
	path 3	path 3 < 5.2 (1) μW			
	after external zeroing <sup>6, 7</sup>				
	path 1	< 114 (67)	pW		
	path 2	< 11 (6) nV	<b>/</b>	(): typical at 1 GHz	
	path 3	< 1.1 (0.6)	μW	+15 °C to +35 °C	
Zero drift <sup>8</sup>	path 1	< 39 (0) pV	<b>/</b>		
	path 2	< 3.3 (0) n\	N		
	path 3	< 0.33 (0) µ	Wı		
Measurement noise 9	path 1	< 72 (42) p	W		
	path 2	< 7 (4) nW			
	path 3	< 0.7 (0.4)	< 0.7 (0.4) µW		

### Uncertainty for absolute power measurements 10 in dB

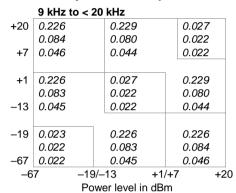








## Uncertainty for relative power measurements 11 in dB



IIIEIII	is iii ui	•			
	20 kHz to	< 100 MHz			
+20	0.206	0.215	0.027		0 °C to +50 °C
	0.082	0.078	0.022		+15 °C to +35 °C
+7	0.046	0.044	0.022		+20 °C to +25 °C
+1	0.205	0.027	0.215		0 °C to +50 °C
	0.081	0.022	0.078		+15 °C to +35 °C
-13	0.044	0.022	0.044		+20 °C to +25 °C
-19	0.023	0.205	0.206		0 °C to +50 °C
	0.022	0.081	0.082		+15 °C to +35 °C
-67	0.022	0.044	0.046		+20 °C to +25 °C
-6	7 –1	9/–13 +1	I/ <del>+</del> 7	+20	
	Р	ower level in o	dBm		

	100 MHz	to 4 (	GHz			
+20	0.209		0.218		0.038	
	0.088		0.085		0.032	
+7	0.055		0.047		0.031	
+1	0.206		0.028		0.218	
	0.083		0.022		0.085	
-13	0.048	.048			0.047	
-19	0.023		0.206		0.209	
	0.022		0.083		0.088	
-67	0.022		0.048		0.055	
<b>−67 −19</b> /			13	+1/+7	+20	
Power level in dBm						

	> 4 GHz to	6 GHz					
+20	0.215	0.223	0.049	0 °C to +50 °C			
	0.097	0.093	0.044	+15 °C to +35 °C			
+7	0.066	0.059	0.043	+20 °C to +25 °C			
+1	0.210	0.030	0.223	0 °C to +50 °C			
	0.088	0.022	0.093	+15 °C to +35 °C			
-13	0.054	0.022	0.059	+20 °C to +25 °C			
-19	0.024	0.210	0.215	0 °C to +50 °C			
	0.022	0.088	0.097	+15 °C to +35 °C			
-67	0.022	0.054	0.066	+20 °C to +25 °C			
-6	7 –1	9/–13 +1/	/+7 +20				
Power level in dBm							

# Additional characteristics of the R&S®NRP-Z28/-Z98 level control sensors

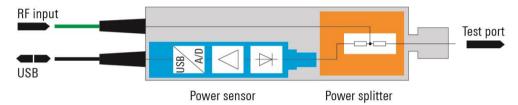
Shaded areas apply only to the R&S®NRP-Z28.

Sensor type		three-path diode power sensor combined with a resistive power splitter in a power leveling setup			
		(see diagram at the end of this section)			
Measurand		power available on a 50 Ω load			
		power of wave emanating at RF output 12			
RF connectors		N (male)			
Measurement functions	stationary and recurring waveforms	continuous average			
		burst average			
		timeslot/gate average			
		trace			
	single events	trace			
Continuous average function	measurand	mean power over recurring acquisition interval			
_	aperture				
	R&S®NRP-Z28	10 μs to 300 ms (20 ms default)			
	R&S®NRP-Z98	1 ms to 300 ms (20 ms default)			
	window function	uniform or von Hann 14			
	duty cycle correction <sup>15</sup>	0.001 % to 99.999 %			
	capacity of measurement buffer 16	1 to 1024 results			
Burst average function	measurand	mean power over burst portion of recurring			
		signal (trigger settings required)			
	detectable burst width	20 µs to 50 ms			
	minimum gap between bursts	10 µs			
	dropout period <sup>17</sup> for burst end	0 s to 3 ms			
	detection	0 3 10 0 1113			
	exclusion periods <sup>18</sup>				
	start 0 to burst width				
	end	0 s to 3 ms			
	resolution (dropout and exclusion	sample period (≈ 8 µs)			
	periods)	sample periou (≈ ο μs)			
Timeslot/gate average function	measurand	mean power over individual timeslots/gates of recurring signal			
	number of timeslots/gates	1 to 128 (consecutive)			
	nominal length	10 μs to 0.1 s			
	start of first timeslot/gate	at delayed trigger event			
	exclusion periods 18				
	start	0 to nominal length			
	end	0 s to 3 ms			
	resolution (nominal length and	sample period (≈ 8 µs)			
	exclusion periods)				
Trace function	measurand	mean power over pixel length			
	acquisition				
	length (△)	100 µs to 300 ms			
	start (referenced to delayed trigger)	–5 ms to +100 s			
	result				
	pixels (M)	1 to 1024			
	resolution (Δ/M)				
	non recurring or internally	≥ 10 µs			
	triggered	- 10 po			
	recurring and externally	≥ 2.5 µs			
	triggered	- Δ.0 μο			

## Shaded areas apply only to the R&S®NRP-Z28.

Averaging filter	modes	auto off(fixed averaging number)			
Avoidying inter	modes	auto on(continuously auto-adapted)			
		auto once(automatically fixed once)			
	auto off	auto chockationialionily linea chock			
	supported measurement functions	all			
	averaging number	$2^N$ ; $N = 0$ to 16 (13 for trace function)			
	auto on/once	, , , , , , , , , , , , , , , , , , , ,			
	supported measurement functions	continuous average, burst average, timeslot/gate average			
	normal operating mode	averaging number adapted to resolution setting and power to be measured			
	fixed noise operating mode	averaging number adapted to specified noise content			
	result output				
	moving mode	continuous, independent of averaging number			
	rate	can be limited to 0.1 s <sup>-1</sup>			
	repeat mode	only final result			
Attenuation correction	function	corrects the measurement result by means of a			
		fixed factor (dB offset)			
	range	-200.000 dB to +200.000 dB			
Embedding	function	incorporates a two-port device at the			
		RF output so that the measurement plane is			
	parameters	shifted to the output of this device			
	parameters	S <sub>11</sub> , S <sub>21</sub> , S <sub>12</sub> and S <sub>22</sub> of device 1 to 1000			
Gamma correction	frequencies function	removes the influence of impedance mismatch			
Gainina correction	Tunction	from the measurement result so that the power			
		of the wave emanating at the RF output can be			
		read			
	parameters	magnitude and phase of reflection coefficient of			
	Ference	DUT			
Frequency response correction	function	takes the frequency response of the sensor			
		section and of the power splitter into account			
	parameter	center frequency of test signal			
	residual uncertainty	see specification of calibration uncertainty and			
		uncertainty for absolute and relative power			
Measurement time 19	continuous average	measurements			
weasurement time "	continuous average R&S®NRP-Z28	$2 \times (aperture + 145 \mu s) \times 2^N + t_z$			
2 <sup>N</sup> : averaging number	NO INIT-ZZO	$2 \times (aperture + 145  \mu s) \times 2^{-1} + t_z$ $t_z : < 1.6  ms$			
T: set number of timeslots	R&S®NRP-Z98	$\frac{t_z}{2} \times (1.0 \text{ ms})$ 2 × (aperture + 5 ms) × 2 <sup>N</sup> – 3.4 ms + $t_d$			
w: nominal length of timeslot	100 NN 200	$t_d$ must be taken into account with activated auto			
		delay (1 ms to 20 ms depending on			
		temperature) <sup>37</sup>			
	buffered <sup>16</sup> , without averaging	$2 \times (\text{aperture} + 250 \mu\text{s}) \times \text{buffer size} + t_z$			
	timeslot/gate average	, , , , , , , , , , , , , , , , , , , ,			
	signal period – T × w > 100 μs	$\leq 2 \times \text{signal period} \times (2^N + \frac{1}{2}) + t_z$			
	all other cases	$\leq 4 \times \text{signal period} \times (2^N + \frac{1}{4}) + t_z$			
Zeroing (duration)	depends on setting of averaging filter				
	auto on	4 s			
	auto off, integration time 20				
	< 4 s	4 s			
	4 s to 16 s	integration time			
	> 16 s	16 s			
Measurement error due to		n=2 $n=3$			
harmonics <sup>21</sup>	-30 dBc	< 0.001 dB < 0.003 dB n: multiple			
	–20 dBc	< 0.002 dB < 0.010 dB of carrier frequency			
	-10 dBc	< 0.010 dB < 0.040 dB			

Measurement error due to modulation <sup>22</sup>	general	depends on ( signal	depends on CCDF and RF bandwidth of to signal		
	WCDMA (3GPP test model 1-64)	·			
	worst case -0.02 dB to +0.07 dB				
	typical	-0.01 dB to +	-0.03 dB		
Calibration uncertainty 24		path 1	path 2	path 3	
(R&S®NRP-Z98 up to 6 GHz only)	< 100 MHz	0.056 dB	0.047 dB	0.048 dB	
	100 MHz to 4.0 GHz	0.066 dB	0.057 dB	0.058 dB	
	> 4.0 GHz to 8.0 GHz	0.083 dB	0.072 dB	0.072 dB	
	> 8.0 GHz to 12.4 GHz	0.095 dB	0.077 dB	0.077 dB	
	> 12.4 GHz to 18.0 GHz	0.124 dB	0.100 dB	0.101 dB	
Interface to host	power supply	+5 V/0.2 A (USB high-power device)			
	remote control		as a USB device (function) in full-speed mode, compatible with USB 1.0/1.1/2.0 specifications		
	trigger input	<u> </u>	differential (0 V/+3.3 V)		
	connector type	ODU Mini-Sn	ODU Mini-Snap® L series,		
		six-pole cylin	drical straight plu	g	
	permissible total cable length	≤ 10 m (see a	≤ 10 m (see also tables on page 28)		
Dimensions	W×H×L	48 mm × 50 r	nm × 250 mm		
		(1.89 in × 1.9	7 in × 9.84 in)		
	length including connecting cable	approx. 1.75	approx. 1.75 m (68.89 in)		
Weight		< 0.7 kg (1.54	1 lb)		



Block diagram of the R&S®NRP-Z28/-Z98 level control sensors

# Power sensor modules in R&S®Smart Sensor Technology

# R&S®NRP-Z27/-Z37 power sensor modules

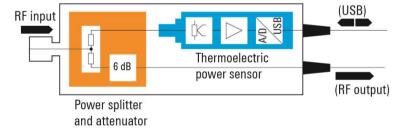
Specifications from 18 GHz to 26.5 GHz apply only to the R&S®NRP-Z37.

Frequency range	R&S®NRP-Z27	DC to 18 GHz	DC to 18 GHz			
	R&S®NRP-Z37	DC to 26.5 GH	lz			
Impedance matching (SWR)	RF input	R&S®NRP-Z2	7 R&S	R&S®NRP-Z37		
	DC to 2.0 GHz	< 1.15	< 1.			
	> 2.0 GHz to 4.2 GHz	< 1.18	< 1.	18		
	> 4.2 GHz to 8.0 GHz	< 1.23	< 1.2	23		
	> 8.0 GHz to 12.4 GHz	< 1.25	< 1.2	25		
	> 12.4 GHz to 18.0 GHz	< 1.35	< 1.3	30		
	> 18.0 GHz to 26.5 GHz	-	< 1.4	45		
	RF output	R&S®NRP-Z2	7 R&S	®NRP-Z37		
	DC to 8.0 GHz	< 1.6	< 1.0	6		
	> 8.0 GHz to 26.5 GHz	< 2.0	< 2.0	0		
Power measurement range		4 µW to 400 m	W (-24 dBm to	+26 dBm),		
-		continuous, in	a single range	,		
Max. power	average power		sm), continuous			
			sm) for max. 10 n	ninutes		
	peak envelope power		) for max. 1 µs			
Acquisition	sample rate	20.833 kHz (s				
Zero offset	after external zeroing 6, 7	< 400 nW (typ	< 400 nW (typically 200 nW at			
Zero drift <sup>8</sup>	- J	< 160 nW				
Measurement noise 9		< 240 nW (typ	< 240 nW (typically 120 nW at 1 GHz)			
Uncertainty for absolute power		+20 °C to +15 °C		0 °C to		
measurements 38		+25 °C	+35 °C	+50 °C		
measurements	with matched load on RF output (SWR < 1.05)					
	DC to < 100 MHz	0.070 dB	0.077 dB	0.103 dB		
	100 MHz to 4.2 GHz	0.075 dB	0.082 dB	0.106 dB		
	> 4.2 GHz to 8.0 GHz	0.087 dB	0.094 dB	0.119 dB		
	> 8.0 GHz to 12.4 GHz	0.093 dB	0.101 dB	0.130 dB		
	> 12.4 GHz to 18.0 GHz	0.112 dB	0.121 dB	0.151 dB		
	> 18.0 GHz to 26.5 GHz	0.122 dB	0.137 dB	0.190 dB		
	with R&S®FSMR26 connected to R			1 22 3		
	DC to < 100 MHz	0.104 dB	0.109 dB	0.128 dB		
	100 MHz to 4.2 GHz	0.116 dB	0.120 dB	0.138 dB		
	> 4.2 GHz to 8.0 GHz	0.163 dB	0.166 dB	0.181 dB		
	> 8.0 GHz to 18.0 GHz	0.183 dB	0.187 dB	0.207 dB		
	> 18.0 GHz to 26.5 GHz	0.226 dB	0.235 dB	0.269 dB		
	with R&S®FSMR26 connected to R					
	DC to < 100 MHz	0.067 dB	0.074 dB	0.101 dB		
	100 MHz to 4.2 GHz	0.077 dB	0.083 dB	0.107 dB		
	> 4.2 GHz to 8.0 GHz	0.092 dB	0.099 dB	0.123 dB		
	> 8.0 GHz to 12.4 GHz	0.092 dB	0.107 dB	0.135 dB		
	> 12.4 GHz to 18.0 GHz	0.122 dB	0.130 dB	0.159 dB		
	> 18.0 GHz to 26.5 GHz	0.154 dB	0.167 dB	0.139 dB		
Uncertainty for relative power	> 10.0 OF 12 to 20.0 OF 12	0.032 dB	0.107 GD	0.2 12 00		
measurements 39		0.032 00				

# Additional characteristics of the R&S®NRP-Z27/-Z37 power sensor modules

Sensor type		thermoelectric power sensor with signal pick-off at RF output (see diagram at the end of this		
Measurand		section) power of incident wave		
Wieasuranu		power of incident wave	nto EO O 12	
RF connectors	input	power of source (DOT) i	1110 30 12	
Kr connectors	R&S®NRP-Z27	N (male)		
	R&S®NRP-Z37	3.5 mm (male)		
	RF signal output	3.5 mm (male)		
Insertion loss	DC to 2.0 GHz	< <b>14</b> (12.5) dB		
Between RF input and RF output	> 2.0 GHz to 4.2 GHz	< <b>15</b> (13.5) dB		
between Kr input and Kr output	> 4.2 GHz to 8.0 GHz	< <b>16</b> (14.0) dB	(): typical	
			( ). typicai	
	> 8.0 GHz to 12.4 GHz	< 17 (14.5) dB		
	> 12.4 GHz to 18.0 GHz > 18.0 GHz to 26.5 GHz	< 18 (15.5) dB		
Management from attack		< <b>19</b> (16.5) dB		
Measurement function	stationary and recurring waveforms	continuous average	in a constation into mod	
Continuous average function	measurand	mean power over recurr		
	aperture	1 ms to 100 ms (20 ms (	uerauit)	
	window function	uniform or von Hann 14		
	duty cycle correction 1515	0.001 % to 99.999 %		
A.v.a.a.a.i.a.a.filta.a.	capacity of measurement buffer 16	1 to 1024 results		
Averaging filter	modes	auto off (fixed averaging	<u> </u>	
		auto on (continuously au		
	. "	auto once (automatically fixed once)		
	auto off	00.01.045.40		
	averaging number $2^N$ ; $N = 0$ to 16			
	auto on/once			
	normal operating mode	averaging number adapted to resolution setting and power to be measured		
	fixed noise operating mode	averaging number adapted to specified noise content		
	result output			
	moving mode	continuous, independent of averaging num		
	rate	can be limited to 0.1 s <sup>-1</sup>		
	repeat mode	only final result		
Attenuation correction	function	corrects the measurement result by means		
		fixed factor (dB offset)		
	range	-200.000 dB to +200.00	0 dB	
Gamma correction	function	removes the influence o	f impedance mismatch	
		from the measurement r	esult so that the power	
		of the source (DUT) into	50 Ω can be read	
	parameters	magnitude and phase of source (DUT)	reflection coefficient of	
Frequency response correction	function	takes the frequency resp		
		section and of the power splitter into account		
	parameter	center frequency of test		
	residual uncertainty	see specification of calibration uncertainty ar		
Landintonformer	formation	uncertainty for absolute		
Load interference correction	function	removing the influence of		
		signal output from the po	ower measurement	
		result	i madi anti ana anni di interiore di	
	parameters	magnitude and phase of reflection coefficient of load see specification of load interference error		

Measurement time 19		2 x (aperture + 450 μs) x	$2^{N} + 4 \text{ ms} + t_{d}$			
2 <sup>N</sup> : averaging number		t <sub>d</sub> (80 ms) must be taken in	nto account when auto			
		delay 37 is active				
Zeroing (duration)	depends on setting of averaging filter					
	auto on					
	auto off, integration time 20					
	< 4 s	4 s				
	4 s to 16 s	integration time				
	> 16 s	16 s				
Calibration uncertainty 40	DC to < 100 MHz	0.063 dB				
	100 MHz to 4.2 GHz	0.070 dB				
	> 4.2 GHz to 8.0 GHz	0.082 dB				
	> 8.0 GHz to 12.4 GHz	0.088 dB				
	> 12.4 GHz to 18.0 GHz	0.109 dB				
	> 18.0 GHz to 26.5 GHz	0.118 dB				
Temperature effect 41	DC to 4.2 GHz	< 0.004 dB/K				
	> 4.2 GHz to 8.0 GHz	< 0.005 dB/K				
	> 8.0 GHz to 12.4 GHz	< 0.005 dB/K				
	> 12.4 GHz to 18.0 GHz	< 0.006 dB/K				
	> 18.0 GHz to 26.5 GHz	< 0.009 dB/K				
Linearity 42	for power levels < 100 mW (20 dBm)	< 0.020 dB				
Power coefficient 43		< (0.02 + 0.002 f/GHz) dB	W			
Load interference error 44	DC to 2.0 GHz	< 0.061 (0.003) dB	values in () after			
From RF signal output	> 2.0 GHz to 12.4 GHz	< 0.050 (0.012) dB	load interference			
	> 12.4 GHz to 18.0 GHz	< 0.043 (0.016) dB	correction			
	> 18.0 GHz to 26.5 GHz	< 0.043 (0.022) dB				
Interface to host	power supply	+5 V/0.1 A (USB low-power				
	remote control	as a USB device (function	) in full-speed mode,			
		compatible with USB 1.0/1	1.1/2.0 specifications			
	trigger input	differential (0 V/+3.3 V)				
	connector type	ODU Mini-Snap® L series,				
		six-pole cylindrical straight plug				
	permissible cable length	≤ 10 m (see also tables on page 28)				
Dimensions	W×H×L	48 mm × 50 mm × 250 mr				
		(1.89 in × 1.97 in × 9.84 in	1)			
	length including connecting cable	approx. 1.75 m (68.89 in)				
Weight		< 0.7 kg (1.54 lb)				



Block diagram of the R&S®NRP-Z27/-Z37 power sensor modules

# **Accessories for sensors**

## R&S®NRP-Z2 extension cables

Application		for extending the connection between an R&S®NRP-Zxx power sensor and the R&S®NRX base unit, another Rohde & Schwarz measuring instrument, an R&S®NRP-Z3/-Z4 USB adapter cable or an R&S®NRP-Z5 USB sensor hub			
Connectors	type	ODU Mini-Snap® L series, size 1, six-pole receptacle			
	sensor side				
	models .03/.05/.10	with in-line receptacle			
	model .15	with bulkhead receptacle for panel mounting			
		< 5 mm wall thickness			
	host side	straight plug			
Length	model .03	1.5 m			
	models .05/.15	3.5 m			
	model .10	8.5 m			
Permissible total length	including power sensor and R&S®NRX base unit or R&S®NRP-Z3/-Z4 USB adapter cable or R&S®NRP-Z5 USB sensor hub, if applicable	see tables below			

Supported combinations with R&S®NRX base unit or other Rohde & Schwarz measuring instruments with ODU Mini-Snap® receptacle (e.g. R&S®FSMR, R&S®SMA200A, R&S®SMF100A)

R&S®NRP-Zxx		R&S®NRF	-Z2 models			total	(shaded combination only
power sensor		.03	.05/.15	.10		length	supported by R&S®NRX
					_	in m	base unit; not permissible
•	+	•	_	_	=	3.0	for R&S®NRP-Z81/-Z85/-Z86
•		_	•	_		5.0	power sensors)
•		_	_	•		10.0	

Supported combinations with R&S®NRP-Z3/-Z4 USB adapter cables

R&S®NRP-Zxx power sensor		R&S®NRP-Z2 models			R&S®NRP-Z4 models			R&S®NRP-Z3/-Z4 model	total length	
		.03	.05/.15		.06	.04	.11	.02		in m
•		_	_		•	_	_	_		1.6
•		_	_		_	•	_	_		2.0
•		_	_		_	_	•	_		2.5
•	+	_	_	+	_	_	_	•	=	3.5
•		•	_		_	_	_	•		5.0
•		_	•		•	_	_	_		5.1
•		_	•		_	•	_	_		5.5
•		_	•		_	_	•	_		6.0
•		_	•		_	_	_	•		7.0

(shaded combinations not permissible for R&S®NRP-Z81/-Z85/-Z86 power sensors)

Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between sensor and hub)

R&S®NRP-Zxx power sensor		R&S®NRI models	P-Z2		R&S®NRP-Z5 USB sensor hub		total length	
	+	.03 .05/.15		+		=	in m	
•	•	•	_	] <b>-</b>	•		3.0	
•		_	•		•		5.0	

Supported combinations with R&S®NRP-Z5 USB sensor hub (cable between hub and host)

R&S®NRP-Z5 USB sensor hub		R&S®NRP-Z2 models		R&S®NRP-Z4 models				standard USB cable (max. length: 5 m)		total length
		.03	.05/.15	.06	.04	.11	.02			in m
•		•	_		_		_	_		3.0
•		_	•		_		_	_		5.0
•	+	_	_	•	_	_	_	_	=	0.1
•		_	_	_	•	_	_	_		0.5
•		_	_	_	_	•	_	_		1.0
•		_	_	_	_	_	•	_		2.0
•		_	_	_	_	_	_	•		5.0

# R&S®NRP-Z3 active USB adapter cable

Application		for connecting an R&S®NRP-Zxx power sensor		
		to a USB host (PC or Rohde & Schwarz		
		measuring instrument with type A receptacle)		
Trigger input	maximum voltage	±15 V		
	logic level			
	low	< 0.8 V		
	high	> 2.0 V		
	input impedance	approx. 5 kΩ		
Connectors	sensor	ODU Mini-Snap® L series, size 1, six-pole		
		receptacle		
	USB host	USB type A plug		
Plug-in power supply	voltage/frequency	100 V to 240 V/50 Hz to 60 Hz		
	tolerance	±10 % for voltage, ±3 Hz for frequency		
	current consumption	25 mA (typ.) with sensor connected		
	connection	via adapter to all common AC supplies		
		(Europe, UK, USA, Australia)		
Dimensions (W × H × L)	USB adapter	48 mm × 45 mm × 140 mm		
		$(1.89 \text{ in} \times 1.77 \text{ in} \times 5.51 \text{ in})$		
	length including connecting cable	approx. 2 m (78.74 in)		
	plug-in power supply	52 mm × 73 mm × 110 mm		
		$(2.05 \text{ in} \times 2.87 \text{ in} \times 4.33 \text{ in})$		
	length of line to USB adapter	approx. 2 m (78.74 in)		
Weight	USB adapter	< 0.2 kg (0.44 lb)		
_	plug-in power supply	< 0.3 kg (0.66 lb)		

# R&S®NRP-Z4 passive USB adapter cable

Application		for connecting an R&S®NRP-Zxx power sensor
		to a USB host (PC or Rohde & Schwarz
		measuring instrument with type A receptacle)
Connectors	sensor side	ODU Mini-Snap® L series, size 1, six-pole
		receptacle
	models .02/.04/.06	with in-line receptacle
	model .11	with bulkhead receptacle for panel mounting
		< 5 mm wall thickness
	host side	USB type A plug
Dimensions (length)	model .02	approx. 2 m (78.74 in)
	model .04	approx. 0.5 m (19.69 in)
	model .06	approx. 0.15 m (5.91 in)
	model .11	approx. 1 m (39.37 in)

# R&S®NRP-Z5 USB sensor hub

Application		for connecting up to four R&S®NRP-Zxx power sensors to  • a USB host (PC or Rohde & Schwarz measuring instrument with type A receptacle)  • a Rohde & Schwarz measuring instrument (other than the R&S®NRX) with circular sensor connector (ODU Mini-Snap® L series, size 1, six-pole receptacle)
Trigger input	maximum voltage	±8 V
	logic level	
	low	< 0.8 V
	high	> 2.0 V
	input impedance	approx. 10 kΩ
	minimum pulse width	35 ns (without R&S®NRP-Z2 extension cable)
Trigger output	high-level output voltage	< 5.3 V (no load), > 2.0 V (50 Ω)
	low-level output voltage	< 0.4 V at 5 mA sink current
Power supply	voltage/power	12 V to 24 V (DC)/24 W
	source	AC adapter supplied with the equipment or
		equivalent DC voltage source
		no supply from extra-low voltage supply systems
		or via secondary cables > 30 m (98.43 ft)
Connectors	sensors A to D	ODU Mini-Snap® L series, size 1, six-pole
		receptacle
	USB host	USB type B receptacle (certified USB 2.0 high-
		speed cable supplied with the equipment)
	for Rohde & Schwarz instrument	ODU Mini-Snap® L series, size 1, six-pole plug
	trigger input, trigger output	BNC receptacle
	power supply	receptacle for DC barrel connector,
		$\varnothing$ 5.5 mm × $\varnothing$ 2.1 mm × 9.5 mm; inner
		conductor is positive pole
Dimensions (W × H × L)	sensor hub	140.6 mm × 36.6 mm × 138 mm
		$(5.54 \text{ in} \times 1.44 \text{ in} \times 5.43 \text{ in})$
Weight	excluding accessories	< 0.55 kg (1.21 lb)
AC adapter	input voltage/frequency	100 V to 240 V/50 Hz to 60 Hz
	tolerance	±10 % for voltage, ±3 Hz for frequency
	input connector	C14 receptacle, in line with IEC 60320
	output voltage/power	12 V (DC)/36 W
	length of secondary cable	approx. 0.72 m (28.35 in)
	dimensions (W x H x L)	120 mm × 52 mm × 31 mm
		(4.72 in × 2.05 in × 1.22 in)
	weight	< 0.3 kg (0.66 lb)

# **General data**

Temperature loading 45	operating and permissible temperature range (in [] if different)	in line with IEC 60068						
	R&S®NRP-Z5 USB sensor hub.	0 °C to +50 °C						
	R&S®NRP-Z3/-Z4 USB adapter cables	0 0 10 +30 0						
	R&S®NRP-Zxx power sensors,	0 °C to +50 °C [–10 °C to +55 °C]						
	R&S®NRP-Z2 extension cables	0 0 10 130 0 [=10 0 10 133 0]						
	storage temperature range							
	R&S®NRP-Z5 USB sensor hub	-40 °C to +70 °C						
	R&S®NRP-Zxx power sensors,	40 0 10 170 0						
	R&S®NRP-Z2 extension cables and							
	R&S®NRP-Z3/-Z4 USB adapter cables							
Climatic resistance	1.00 1.1.1. 25, 24 000 ddapter ddbiod	in line with EN 60068						
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	damp heat	+25 °C/+40 °C cyclic at 95 % relative						
	damp noat	humidity,						
		with restrictions: noncondensing						
lechanical resistance	vibration							
	sinusoidal	5 Hz to 55 Hz, max. 2 g						
	om accida.	55 Hz to 150 Hz, 0.5 g constant,						
		in line with EN 60068						
	random	10 Hz to 500 Hz, 1.9 g (RMS),						
	1-11-1-11	in line with EN 60068						
	shock	40 g shock spectrum,						
		in line with EN 60068						
	air pressure	1						
	operation	795 hPa (2000 m) to 1060 hPa						
	transport	566 hPa (4500 m) to 1060 hPa						
Electromagnetic compatibility	·	in line with EN 61326, EN 55011						
Safety		in line with EN 61010-1, IEC 61010-1,						
-		CAN/CSA-C22.2 No. 61010-1-04,						
		UL STD. No. 61010-1						
Calibration interval	for R&S®NRP-Z8x power sensors	1 year						
	for all other R&S®NRP-Zxx power sensors	2 years						

# **Appendix**

# Reading the uncertainty of diode power sensors for relative power measurements

The example shows a level step of approx. 14 dB (-4 dBm  $\rightarrow$  +10 dBm) at 1.9 GHz and an ambient temperature of +28 °C for an R&S®NRP-Z21 power sensor.



Power Level 2: +10 dBm

# **Ordering information**

Designation	Туре	Order No.
Two-path diode power sensors		
1 nW to 100 mW, 10 MHz to 8 GHz	R&S®NRP-Z211	1417.0409.02
1 nW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z221	1417.0309.02
Wideband power sensors		
1 nW to 100 mW, 50 MHz to 18 GHz	R&S®NRP-Z81	1137.9009.02
1 nW to 100 mW, 50 MHz to 40 GHz (2.92 mm)	R&S®NRP-Z85	1411.7501.02
1 nW to 100 mW, 50 MHz to 40 GHz (2.40 mm)	R&S®NRP-Z86	1417.0109.40
1 nW to 100 mW, 50 MHz to 44 GHz (2.40 mm)	R&S®NRP-Z86	1417.0109.44
Level control sensors		
200 pW to 100 mW, 9 kHz to 6 GHz	R&S®NRP-Z98	1170.8508.02
200 pW to 100 mW, 10 MHz to 18 GHz	R&S®NRP-Z28	1170.8008.02
Power sensor modules		
4 μW to 400 mW, DC to 18 GHz	R&S®NRP-Z27	1169.4102.02
4 μW to 400 mW, DC to 26.5 GHz	R&S®NRP-Z37	1169.3206.02
Recommended extras		
R&S®NRPV virtual power meter (PC application),	R&S®NRPZ-K1	1418.9800.03
activation for one R&S®NRP-Zxx power sensor		
Sensor extension cable to 3 m	R&S®NRP-Z2	1146.6750.03
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.05
Sensor extension cable to 10 m	R&S®NRP-Z2	1146.6750.10
Sensor extension cable to 5 m	R&S®NRP-Z2	1146.6750.15
(with bulkhead receptacle for panel mounting)		
USB adapter cable (active)	R&S®NRP-Z3	1146.7005.02
USB adapter cable (passive, length: 2.0 m)	R&S®NRP-Z4	1146.8001.02
USB adapter cable (passive, length: 0.5 m)	R&S®NRP-Z4	1146.8001.04
USB adapter cable (passive, length: 0.15 m)	R&S®NRP-Z4	1146.8001.06
USB adapter cable (passive, length: 1.0 m, with bulkhead receptacle for	R&S®NRP-Z4	1146.8001.11
panel mounting)		
USB sensor hub	R&S®NRP-Z5	1146.7740.02

Warranty		
R&S®NRX base unit, power sensors and R&S®NRP-Z5	3 years	
All other items <sup>46</sup>	1 year	
Options		
Extended warranty, one year	R&S®WE1	Please contact your local
Extended warranty, two years	R&S®WE2	Rohde & Schwarz sales
Extended warranty with calibration coverage, one year	R&S®CW1	office.
Extended warranty with calibration coverage, two years	R&S®CW2	
Extended warranty with accredited calibration coverage, one year	R&S®AW1	
Extended warranty with accredited calibration coverage, two years	R&S®AW2	

#### Extended warranty with a term of one and two years (WE1 and WE2)

Repairs carried out during the contract term are free of charge <sup>47</sup>. Necessary calibration and adjustments carried out during repairs are also covered.

#### Extended warranty with calibration (CW1 and CW2)

Enhance your extended warranty by adding calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated, inspected and maintained during the term of the contract. It includes all repairs <sup>47</sup> and calibration at the recommended intervals as well as any calibration carried out during repairs or option upgrades.

#### Extended warranty with accredited calibration (AW1 and AW2)

Enhance your extended warranty by adding accredited calibration coverage at a package price. This package ensures that your Rohde & Schwarz product is regularly calibrated under accreditation, inspected and maintained during the term of the contract. It includes all repairs <sup>47</sup> and accredited calibration at the recommended intervals as well as any accredited calibration carried out during repairs or option upgrades.

## **Endnotes**

<sup>1</sup> Specifications apply to timeslots/gates with a duration of 12.5 % referenced to the signal period (duty cycle 1:8). For other waveforms, the following equation applies: lower measurement limit = lower measurement limit for continuous average mode / √(duty cycle).

<sup>2</sup> With a resolution of 256 pixels.

3 Specifications apply to the default transition setting of 0 dB. The transition regions can be shifted by as much as -20 dB using an adequate offset.

<sup>4</sup> To prevent aliasing in the case of signals with discrete modulation frequencies between 100 kHz and 1 MHz.

<sup>5</sup> Time span prior to triggering, where the trigger signal must be entirely below the threshold level in the case of a positive slope and vice versa in the case of a negative slope.

<sup>6</sup> Specifications expressed as an expanded uncertainty with a confidence level of 95 % (two standard deviations). For calculating zero offsets at higher confidence levels, use the properties of the normal distribution (e.g. 99.7 % confidence level for three standard deviations).

<sup>7</sup> Specifications apply to zeroing with a duration of 4 s. Zeroing for more than 4 s lowers uncertainty correspondingly (half values for 16 s).

<sup>8</sup> Within one hour after zeroing, permissible temperature change ±1 °C, following a two-hour warm-up of the power sensor.

<sup>9</sup> Two standard deviations at 10.24 s integration time in continuous average mode, with aperture time set to default value. The integration time is defined as the total time used for signal acquisition, i.e. the product of twice the aperture time and the averaging number. Multiplying the noise specifications by √(10.24 s/integration time) yields the noise contribution at other integration times. Using a von Hann window function increases noise by a factor of 1.22.

Expanded uncertainty (k = 2) for absolute power measurements on CW signals with automatic path selection and the default transition setting of 0 dB. Specifications include calibration uncertainty, linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power measurement at 3.2 nW (–55 dBm) and 1.9 GHz is to be determined for an R&S®NRP-Z11. The ambient temperature is +29 °C and the averaging number is set to 32 in the continuous average mode with an aperture time of 20 ms.

Since path 1 is used for the measurement, the typical absolute uncertainty due to zero offset is 64 pW (typical) after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{3.2 \, nW + 64 \, pW}{3.2 \, nW} = 0.086 \, dB$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 40 pW  $\times \sqrt{(10.24 \text{ s/}(32 \times 2 \times 0.02 \text{ s}))} = 113 \text{ pW}$ , which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{3.2 \, nW + 113 \, pW}{3.2 \, nW} = 0.151 \, dB$$

Combined with the uncertainty of 0.081 dB for absolute power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.086^2 + 0.151^2 + 0.081^2} dB = 0.192 dB$$
.

The contribution of zero drift has been neglected in this case. It must be treated like zero offset if it is relevant for total uncertainty.

11 Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency with automatic path selection and a default transition setting of 0 dB. For reading the measurement uncertainty diagrams of universal, average and level control sensors, see the Appendix.

Specifications include calibration uncertainty (only if different paths are affected), linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –30 dBm for the R&S®NRP-Z211/-Z221. The contribution of measurement noise depends on power and integration time and can be neglected below 0.01 dB.

Example: The uncertainty of a power step from 1 mW (0 dBm) to 10 nW (-50 dBm) at 5.4 GHz is to be determined for an R&S®NRP-Z11. The ambient temperature is +20 °C and the averaging number is set to 16 for both measurements in the continuous average mode with an aperture time of 20 ms. For the calculation of total uncertainty, the relative contribution of noise, zero offset and zero drift must be taken into account for both measurements . In this example, all contributions at 0 dBm and the effect of zero drift have been neolected.

Since path 1 is used for the -50 dBm measurement, the typical absolute uncertainty due to zero offset is 64 pW after external zeroing, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{10 \, nW \, + \, 64 \, pW}{10 \, nW} = 0.028 \, dB$$

Using the formula in endnote 9, the absolute noise contribution of path 1 is typically 40 pW  $\times \sqrt{(10.24 \text{ s/}(16 \times 2 \times 0.02 \text{ s}))}$  = 160 pW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{10 \text{ nW} + 160 \text{ pW}}{10 \text{ nW}} = 0.069 \text{ dB}$$

Combined with the uncertainty of 0.054 dB for relative power measurements under the given conditions, the total expanded uncertainty is

$$\sqrt{0.028^2 + 0.069^2 + 0.054^2} dB = 0.092 dB$$

12 Gamma correction activated.

34

<sup>13</sup> Preceding sensor section (nominal value).

14 Preferably used with determined modulation when the aperture time cannot be matched to the modulation period. Compared to a uniform window, measurement noise is about 22 % higher.

<sup>15</sup> For measuring the power of periodic bursts based on an average power measurement.

- To increase measurement speed, the power sensor can be operated in buffered mode. In this mode, measurement results are stored in a buffer of user-definable size and then output as a block of data when the buffer is full. To enhance measurement speed even further, the sensor can be set to record the entire series of measurements when triggered by a single event. In this case, the power sensor automatically starts a new measurement as soon as it has completed the previous one.
- 17 This parameter enables power measurements on modulated bursts. The parameter must be longer in duration than modulation-induced power drops within the burst.
- <sup>18</sup> To exclude unwanted portions of the signal from the measurement result.
- 19 Valid for Repeat mode, extending from the beginning to the end of all transfers via the USB interface of the power sensor. Measurement times under remote control of the R&S®NRX base unit via IEC/IEEE bus are approximately 2.5 ms longer, extending from the start of the measurement up to when the measurement result has been supplied to the output buffer of the R&S®NRX.
- <sup>20</sup> Integration time is defined as the total time used for signal acquisition, i.e. taking into account the chosen aperture/acquisition time and the averaging
- 21 Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (-10 dBm) for path 1 and 40 mW (+16 dBm) for path 2. Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- Measurement error referenced to a CW signal of equal power and frequency. For the R&S®NRP-Z211/-Z221, specifications apply to automatic path selection and power levels up to +16 dBm or, within a subrange, to 0.1 mW (-10 dBm) for path 1 and 39.8 mW (+16 dBm) for path 2 Above the mentioned power limit, specifications must be raised by a factor of 1.25 per 1 dB rise in power level. Within a subrange, measurement errors are proportional to the measured power in W.
- <sup>23</sup> Applies to the R&S®NRP-Z211/-Z221, referenced to 0 dBm.
- Expanded uncertainty (k = 2) for absolute power measurements on CW signals at the calibration level within a temperature range from +20 °C to +25 °C and at the calibration frequencies (10 MHz, 15 MHz, 20 MHz, 30 MHz, 50 MHz, 100 MHz; in steps of 250 MHz from 250 MHz to the upper frequency limit). Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The calibration level for the R&S®NRP-Z211/-Z221 is -10 dBm for paths 1 and 2.
- <sup>25</sup> With full video bandwidth. Reduce the specified minimum levels according to the reduction of sampling noise at lower bandwidths.
- Specifications are valid from +15 °C to +50 °C ambient temperature. Below +15 °C, video bandwidth and single-shot bandwidth continuously decrease down to 20 MHz (typical) at 0 °C. Accordingly, the sensor rise time increases up to 50 ns for signals below 500 MHz and up to 20 ns for higher frequencies (typical at 0 °C).
- 27 Specifications are valid at +23 °C ambient temperature for power levels ≤ -20 dBm and frequencies ≥ 500 MHz. For measurements at other temperatures levels and/or frequencies, use the multipliers from table A.
- <sup>28</sup> Measured over a one-minute interval, at constant temperature, two standard deviations.
- 29 512k averages taken with the aperture time set to default (10 μs). The measurement noise with other averaging numbers can be calculated by applying the multipliers indicated below:

Averaging number	512k	128k	32k	8k	2k	512	128	32	8
Integration time	10.49 s	2.62 s	655.36 ms	163.84 ms	40.96 ms	10.24 ms	2.56 ms	0.64 ms	0.16 ms
Noise multiplier	1	2	4	8	16	32	64	128	256

Using a von Hann window function further increases noise by a factor of 1.22. Integration time is defined as the total time used for signal acquisition, i.e. the product of twice the aperture time and the averaging number.

The measurement noise is always minimal for the default aperture time. Increasing the aperture time above this value is only useful for suppressing modulation-induced fluctuations of the measurement result, e.g. by matching the aperture time to the modulation period.

Expanded uncertainty (k = 2) for absolute power measurements on CW signals. Specifications include calibration uncertainty, linearity, influence of sensor-induced harmonics reflected on the DUT, and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset and zero drift can be neglected for power levels above –35 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.02 dB.

Example: The power to be measured is 40 nW (-44 dBm) at 12 GHz in the continuous average mode; ambient temperature +35 °C; averaging number set to 32k with an aperture time of 10  $\mu$ s (1 s integration time).

The typical absolute uncertainty due to zero offset is 220 pW at +23 °C. From table A, a multiplier of 1.4 can be taken to read a typical zero offset of 308 pW at +35 °C. The corresponding relative measurement uncertainty can be calculated as follows:

$$10 \times lg \frac{40nW + 308pW}{40nW} = 0.033dB$$

Using the noise multiplier (4) from endnote 29 and the multiplier (1.4) from table A, the absolute noise contribution is typically  $110 \text{ pW} \times 4 \times 1.4 = 616 \text{ pW}$ , which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{40 nW + 616 pW}{40 nW} = 0.066 dB$$

Combined with the value of 0.18 dB specified for the uncertainty of absolute power measurements at 12 GHz, the total expanded uncertainty is

$$\sqrt{0.18^2 + 0.033^2 + 0.066^2} \, dB = 0.195 \, dB$$

The contribution of zero drift has been neglected in this case. It must be treated like zero offset if it is relevant for total uncertainty.

31 Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency, carried out using a matched source. For reading the measurement uncertainty, see the Appendix. For small power ratios up to 5 dB, expanded uncertainty will typically not exceed 0.06 dB (0.08 dB) at +23°C (from 0°C to +50°C).

Specifications include linearity of the sensor, influence of sensor-induced harmonics that may be re-reflected at the source (DUT), and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset and zero drift can be neglected for power levels above –35 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below a two-sigma value of 0.02 dB. A source (DUT) SWR of 3 has been assumed for signal frequency harmonics emanating from the sensor.

Example: The uncertainty of a power step from 1 mW (0 dBm) to 1  $\mu$ W (-30 dBm) at 31 GHz is to be determined with an R&S $^{\circ}$ NRP-Z85. The ambient temperature is +21  $^{\circ}$ C and the averaging number is set to 128 for both measurements. Measurements are carried out in the continuous average mode with a default aperture time of 10  $\mu$ s.

For the calculation of total uncertainty, the relative contribution of zero offset and zero drift can be neglected in this case since both power levels are higher than -30 dBm. Noise must be taken into account for measurements at 1  $\mu$ W. Using the noise multiplier (64) from endnote 29 and the multiplier (1.0) from table A, the absolute noise contribution is typically 110 pW × 64 × 1.0 = 7 nW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{1 \mu W + 0.007 \, nW}{1 \, \mu W} = 0.030 \, dB$$

Combined with the uncertainty of 0.126 dB for relative power measurements with a matched source (see table), total expanded uncertainty is

$$\sqrt{0.03^2 + 0.126^2}$$
 dB = 0.130 dB

Mismatch of the source (DUT) at the signal frequency can further impair linearity due to a change of the input reflection coefficient of the power sensor as a function of applied power (for specifications of reflection coefficient changes, see page 13). Limits of the induced linearity error can be approximated by

$$\pm 8.7 \text{ dB} \cdot r_{\text{DUT}} \cdot \Delta r_{\text{SEN}}$$

where  $r_{\text{DUT}}$  denotes the magnitude of the reflection coefficient of the source (DUT) and  $\Delta r_{\text{SEN}}$  denotes the change of the input reflection coefficient of the power sensor.

- 32 Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For power levels below −10 dBm, the specifications for 2 × f₀ (3 × f₀) can be lowered by a factor of √10 (10) per 10 dB below −10 dBm. Example: At 12 GHz/–30 dBm, the influence of the second harmonic, suppressed by 20 dBc, will cause an error of max. 0.25 dB ÷ 10 = 0.025 dB. Standard uncertainties can be assumed to be half the values.
- 33 Magnitude of the change vector in the complex plane.
- <sup>34</sup> Expanded uncertainty (k = 2) for absolute power measurements on CW signals at the calibration level (–10 dBm) within a temperature range from +20 °C to +25 °C and at the calibration frequencies (50/55/60/68/80/100/200/300/400/499.99/500/600/720/850/1000/1500 MHz; R&S®NRP-Z81: in steps of 0.5 GHz from 2 GHz to the upper frequency limit; R&S®NRP-Z85/-Z86: in steps of 1 GHz from 2 GHz to 26 GHz and in steps of 0.5 GHz from 26.5 GHz to 44 GHz). Specifications include zero offset and measurement noise (up to a 2σ value of 0.01 dB).
- 35 Equivalent source SWR.
- <sup>36</sup> Between RF input and RF output (test port).
- 37 With activated auto delay, the beginning of a measurement sequence is delayed so that settled readings are obtained even if the measurement command (remote trigger) coincides with a signal step up to ±10 dB.
- Expanded uncertainty (k = 2) for absolute power measurements up to 100 mW (+20 dBm) at the calibration frequencies (see endnote 40). Specifications include calibration uncertainty, linearity, temperature effect and interference from the wave reflected by the load on the RF output. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. If the measured power exceeds 100 mW, the power coefficient of the integrated power splitter must be taken into account (see endnote 43). As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB.

Example: The power to be measured with an R&S®NRP-Z37 is 50  $\mu$ W (–13 dBm) at 19 GHz; ambient temperature +29  $^{\circ}$ C; averaging number set to 64 in continuous average mode with an aperture time of 20 ms.

The maximum absolute uncertainty due to zero offset (after external zeroing) is 400 nW, which corresponds to a relative measurement uncertainty of

$$10 \times lg \, \frac{50 \, \mu W + \, 400 \, nW}{50 \, \mu W} = 0.035 \, dB$$

Using the formula in endnote 9, the maximum absolute noise contribution is 240 nW  $\times \sqrt{(10.24 \text{ s}/(64 \times 2 \times 0.02 \text{ s}))} = 480 \text{ nW}$ , which corresponds to a relative measurement uncertainty of

$$10 \times lg \frac{50 \,\mu W + 480 \,nW}{50 \,\mu W} = 0.042 \,dB$$

Combined with the value of 0.137 dB specified for the uncertainty of absolute power measurements, the total expanded uncertainty is

$$\sqrt{0.035^2 + 0.042^2 + 0.137^2} \, dB = 0.148 \, dB$$

- <sup>39</sup> Expanded uncertainty (k = 2) for relative power measurements on CW signals of the same frequency. Specifications include linearity and temperature effect. Zero offset, zero drift and measurement noise must additionally be taken into account when measuring low powers. As a rule of thumb, the contribution of zero offset can be neglected for power levels above –7 dBm if external zeroing has been applied. The contribution of measurement noise can be neglected below 0.01 dB. See also the example in endnote 9 for taking into account zero offset and noise with relative measurements.
- <sup>40</sup> Expanded uncertainty (k = 2) for absolute power measurements at the calibration level (0 dBm) within a temperature range from +20 °C to +25 °C and at the calibration frequencies. Specifications include zero offset and measurement noise (up to a 2σ value of 0.004 dB). The load on the RF signal output must be of a low-reflection type (SWR < 1.05) or load interference correction must be applied.</p>

Calibration frequencies: 0.1/0.5/1/3/5/10/50/100 MHz; in steps of 100 MHz from 100 MHz to the upper frequency limit.

- <sup>41</sup> Error of an absolute power measurement with respect to temperature, taking into account the power sensor section, the power splitter and the RF cable (temperature-dependent interference from the load on the RF signal output due to phase change).
- <sup>42</sup> Expanded uncertainty for relative power measurements on CW signals of the same frequency, referenced to the calibration level (0 dBm) and excluding zero offset, zero drift and measurement noise.
- <sup>43</sup> Maximum change of insertion loss of the power splitter with respect to input power, leading to an equivalent measurement error of the power sensor module and a change of the power available at the RF signal output. The power coefficient should be taken into account if the input power exceeds 100 mW (+20 dBm).
- <sup>44</sup> Measurement error due to interference of the wave reflected by a mismatched load on the RF signal output. Specifications are indicated for a 0.1 reflection coefficient of the load. Since the load interference error is proportional to the amplitude of the reflected wave, half (twice) the values will be encountered for a reflection coefficient of 0.05 (0.2). The error introduced by an R&S®FSMR26 at the RF signal output does not exceed ±0.06 dB from DC to 2 GHz, ±0.10 dB up to 18 GHz, and ±0.14 dB up to 26.5 GHz.
  - Values in ( ) represent residual error contribution after numeric load interference correction. This correction function requires the complex reflection coefficient of the load to be transferred to the power sensor module. The residual error contribution of an R&S®FSMR26 at the RF signal output does not exceed ±0.003 dB from DC to 2 GHz, ±0.04 dB up to 18 GHz, and ±0.07 dB up to 26.5 GHz.
- <sup>45</sup> The operating temperature range defines the span of ambient temperature in which the instrument complies with specifications. In the permissible temperature range, the instrument is still functioning but compliance with specifications is not warranted.
- 46 For options that are installed, the remaining base unit warranty applies if longer than 1 year. Exception: all batteries have a 1 year warranty.
- <sup>47</sup> Excluding defects caused by incorrect operation or handling and force majeure. Wear-and-tear parts are not included.

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